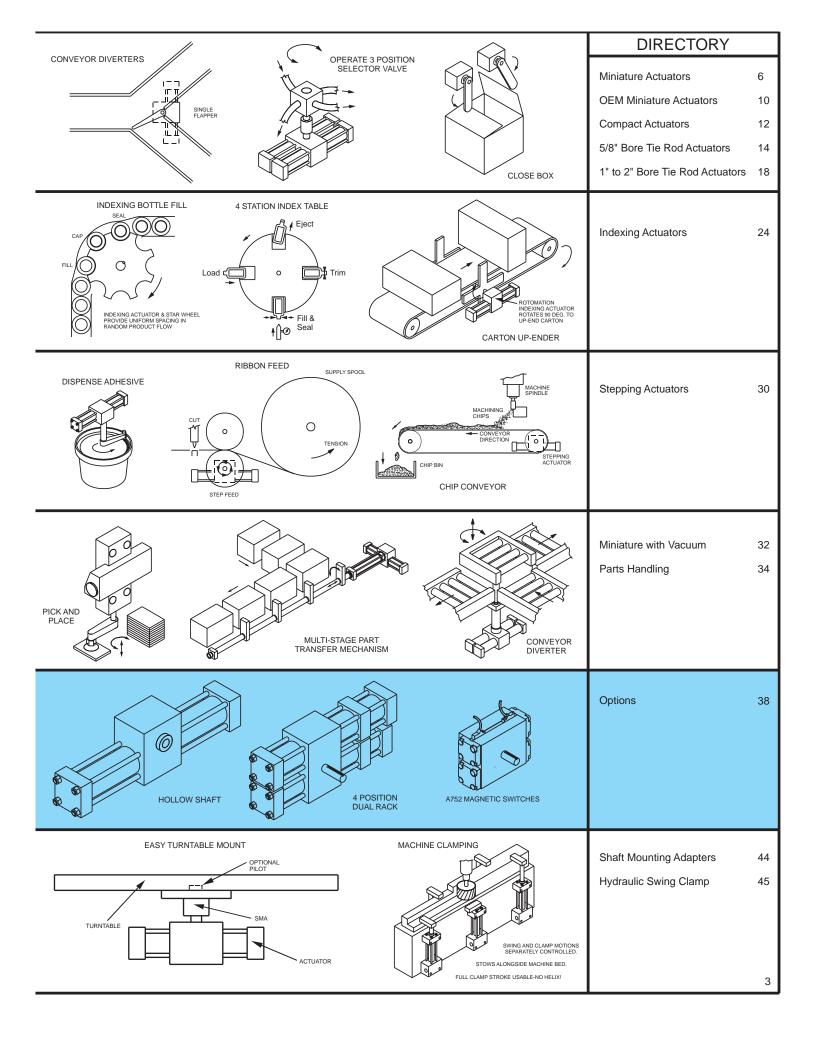
# (R)OTOMATION!

THE SHAFT MOTIONS COMPANY



**FLUID POWER FOR AUTOMATION** 

ROTARY ACTUATORS	Back and Forth Windshield Wiper Motion Optional Stops at Multiple Positions in any Sequence	A032 A42 A752
INDEXING ACTUATORS	One Way Rotation in Steps to Hard Stops Steps 12 to 360 Degrees No Accumulating Error	X4 X1
STEPPING ACTUATORS	One Way Rotation in Steps Without Hard Stops Steps in Any Angle Available	S4 S1
PICK & PLACE ACTUATORS	Back and Forth Rotation, Extend and Retract Independently Driven Miniature with Vacuum Through Rod	PBL3 PA22 PBM3
OPTIONS FOR ACTUATORS	Control Motion  Special Construction  Magnetic Switches  Mount Plates  Shaft Configuration	
OTHER PRODUCTS	Shaft Mounting Adapters Hydraulic Swing Clamp	



# Don't live with "one size fits all"

Select a shaft motion

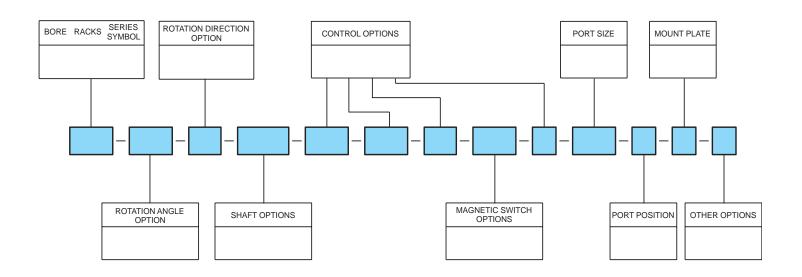
Pick a basic unit

Specify options that serve you best

Get delivery in five days

Pay an off the shelf price

Run reliable production

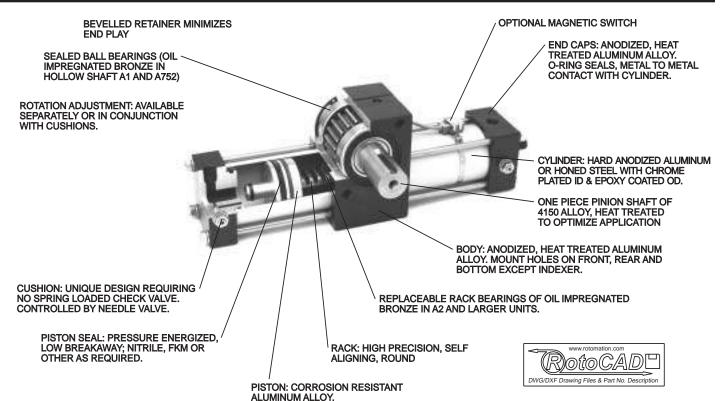


Optimize your application with multiple choices for most parameters; 150 billion standard combinations!

Specials? Send us your sketch and we will quote you one or one thousand.

On time delivery

# ROTOMATION builds actuators, stepping actuators and indexing actuators of proven materials, components and design



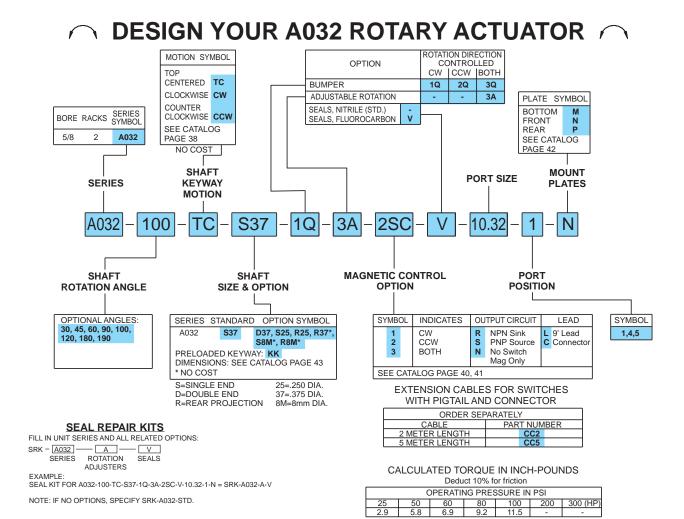
UNITS CONSTRUCTED FOR HEAVY DUTY AND DUST RESISTANCE OR WASHDOWN APPLICATIONS AVAILABLE.

LUBRICATION: LITHIUM BASED GREASE WITH PTFE. SEE INSTALLATION AND MAINTENANCE INSTRUCTIONS.

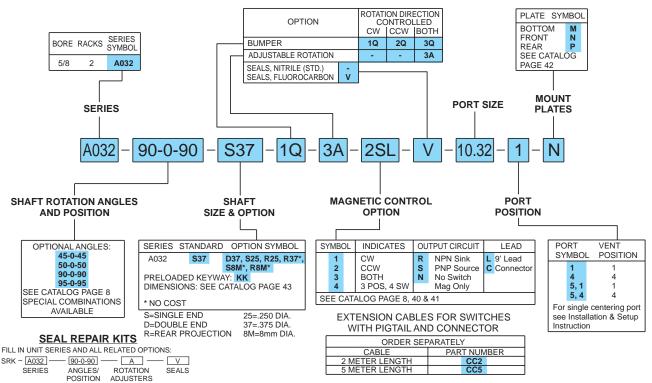
# Performance you can count on

All Rotomation devices except AL75 are of rack and pinion construction to provide a constant torque over entire rotation of their shafts. Their similarities and differences are outlined in the following table.

					COMPOSITE UNITS				
OPERATION	ROTARY ACTUATOR		STEPPING ACTUATOR	INDEXING ACTUATOR	PICK & PLACE ACTUATOR	NITPICKER (INDEXER)			
Shaft Rotation	Back and Forth		One Way	One Way	Back & Forth	One Way			
Rotation Tolerance	A032, A01 A752, A1, A12 A2, A22 A3, A32, A4, A42	<b>-0+</b> 5 <b>-0+</b> 2 <b>-0+</b> 3 -0+2	N/A	All: -0.2	PA01 -0+10 PA2, PA22 -0+3 PA3, PA32 -0+2	PX2 -0.2 PX22 -0.2			
Backlash at end of rotation	ALL DUAL RACK A01 A1, A2 A3, A4	0 2 <b>1</b> .5	N/A	All: 0	PA01 6 PA2, PA3 2 PA22, PA32 1	PX2 1			
Variable Rotation	Optional		Optional	No	Std. On PBL3 & PBM3	No			
Multiple Angles of Rotation	Optional except AL75		Optional	Optional	optional on others Optional except PBL3 & PBM3	Optional			
Shaft Extension and Retraction	No		No	No	Yes	Yes			
Breakaway pressure with standard seals	5 psi		5 psi	7 psi	12 psi	12 psi			



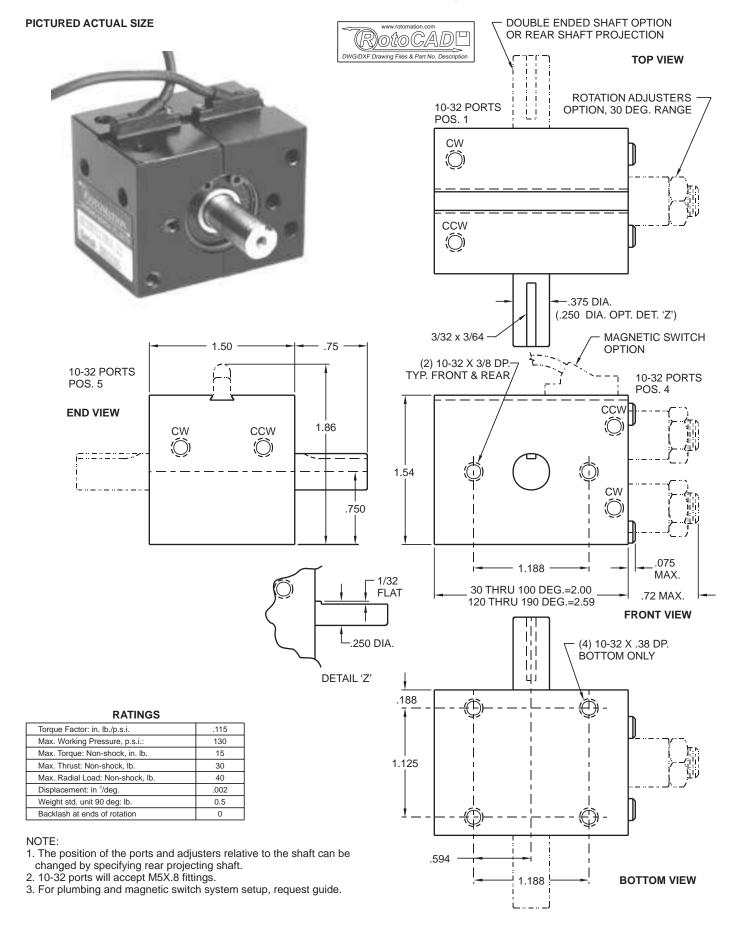
# → DESIGN YOUR A032 THREE POSITION ROTARY ACTUATOR /



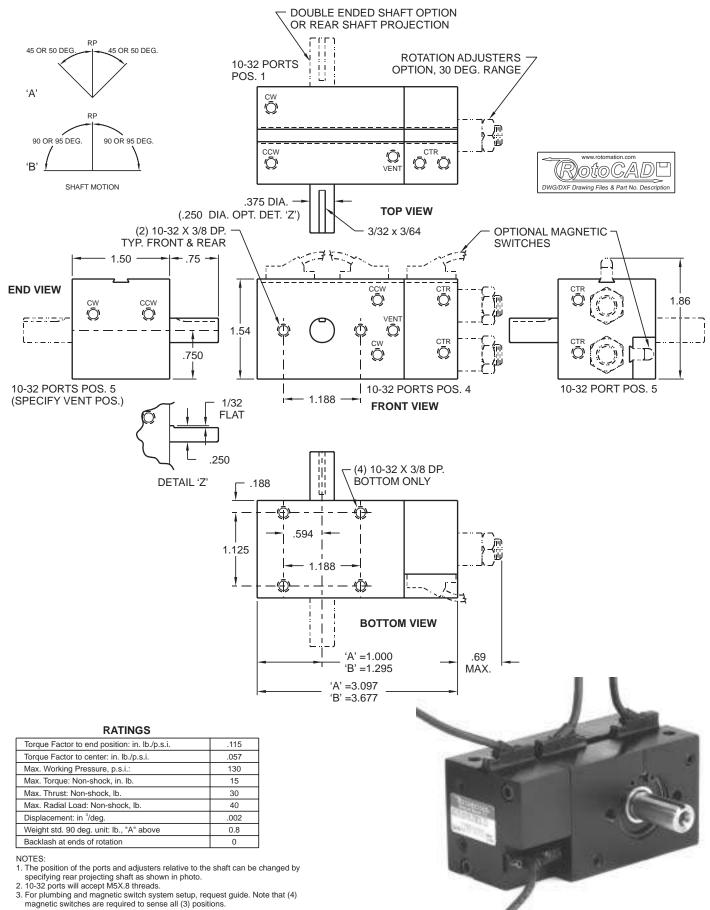
SEAL KIT FOR A032-90-0-90-S37-1Q-3A-2SL-V-10.32-1-N = SRK-A032-90-0-90-A-V

# **A032 SUBMINIATURE DUAL RACK ACTUATOR**

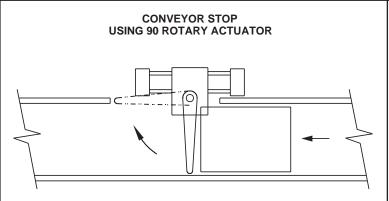
# THE MIGHTIEST MINI -- THE MOST TORQUE FOR ITS SIZE

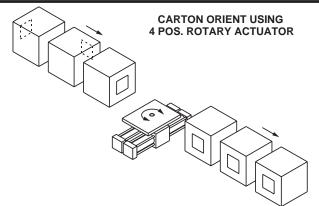


# **A032 SUBMINIATURE THREE POSITION ACTUATOR**



# APPLICATIONS ROTOMATION DOES BETTER MORE PRECISELY

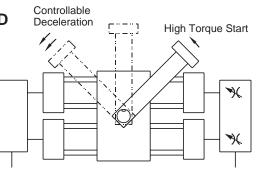


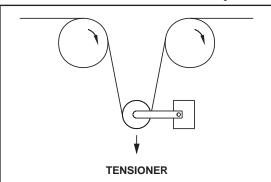


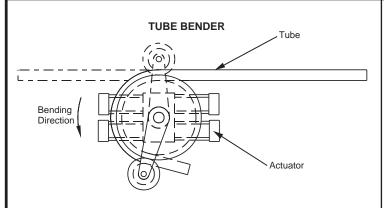
# OVER CENTER LOAD SWING-NO IMPACT

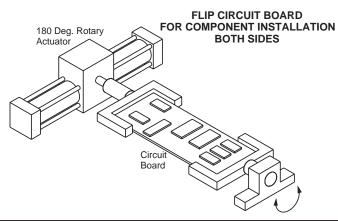
ALL AIR-NO OIL-NO SHOCK ABSORBERS WORKS AT HIGH CYCLE RATES.

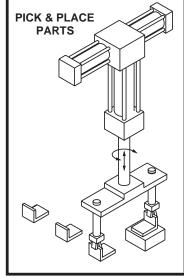
Over Center or Other High Inertia Load Control.

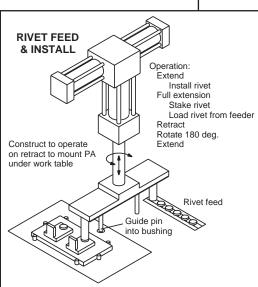


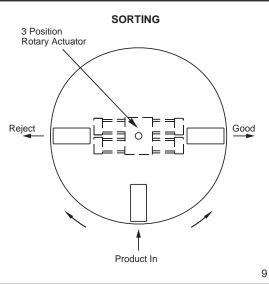




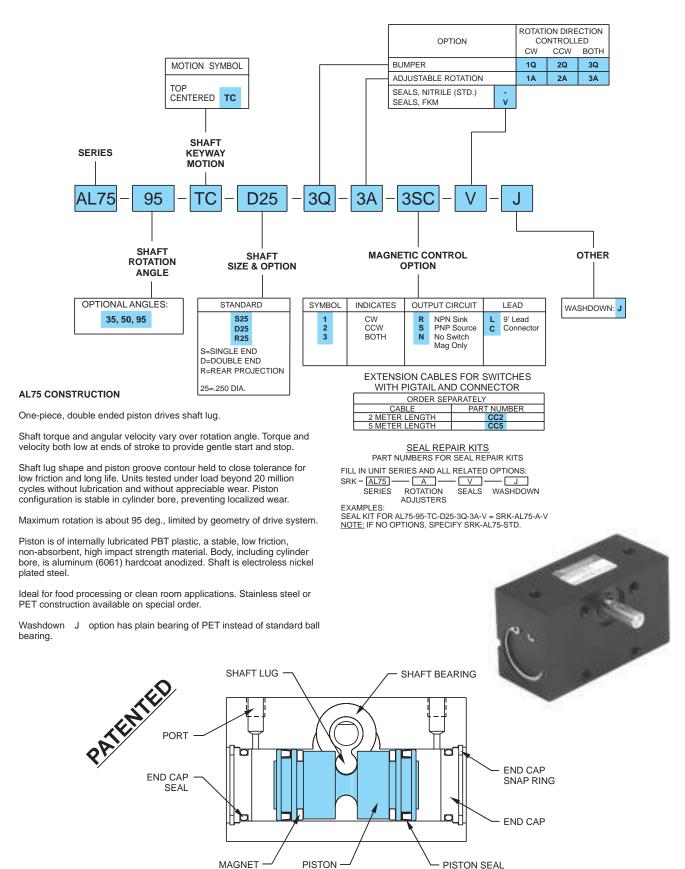




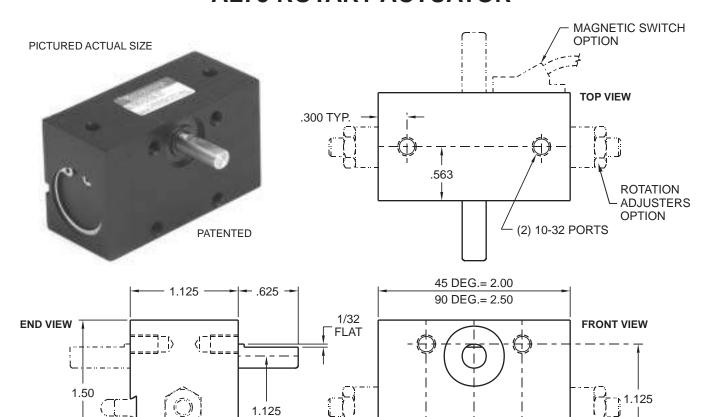




# 

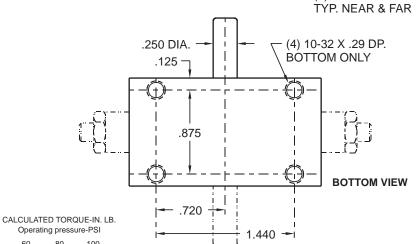


# **AL75 ROTARY ACTUATOR**



### **RATINGS**

Max. Working Pressure: p.s.i.:	100
Max. Torque: Non-shock: in. lb.	14
Max. Load Energy: in. lb.	.25 in. lb.
Max. Thrust Load: lb.	20
Max. Radial Load: lb.	20
Displacement: in ³/deg.	.0012
Weight std. unit 90: lb.	0.3
Backlash at ends of rotation: ded	1

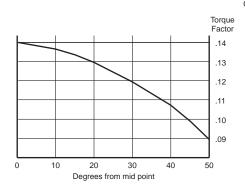


.500

- 1.000

.125

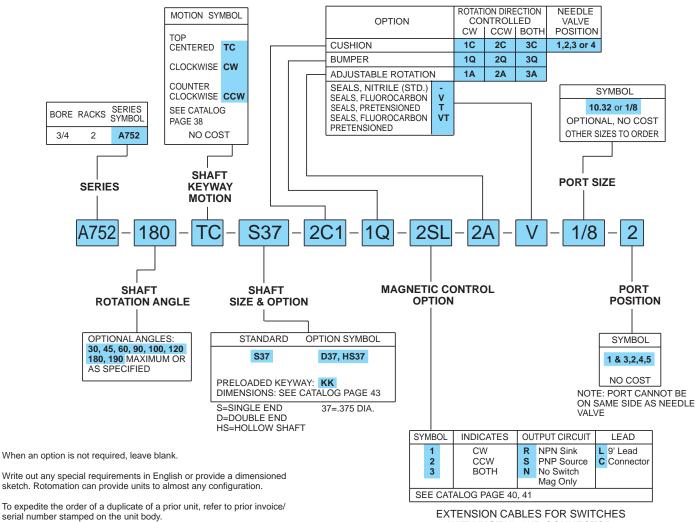
(4) 10-32 X .29 DP.



Operating pressure-PSI							
60	80	100					
8.4	11.2	14					
7.8	10.4	13					
7.2	9.6	12					
6.6	8.8	11					
6	8	10					
5.4	7.2	9					



# 



Write out any special requirements in English or provide a dimensioned

serial number stamped on the unit body.

Needle valve cannot be on same side as port.

# CALCULATED TORQUE IN INCH-POUNDS

Deduct 10% for friction

OPERATING PRESSURE IN PSI							
25	50	60	80	100	200	300 (HP)	
11	22	26.6	35.4	44.2	-	-	

# **FEATURES**

High torque: .44P in. lb. Ball bearings Compact size Roller burnished long life cylinder bores Mounts on base, front or rear face No backlash at ends of rotation



# WITH PIGTAIL AND CONNECTOR

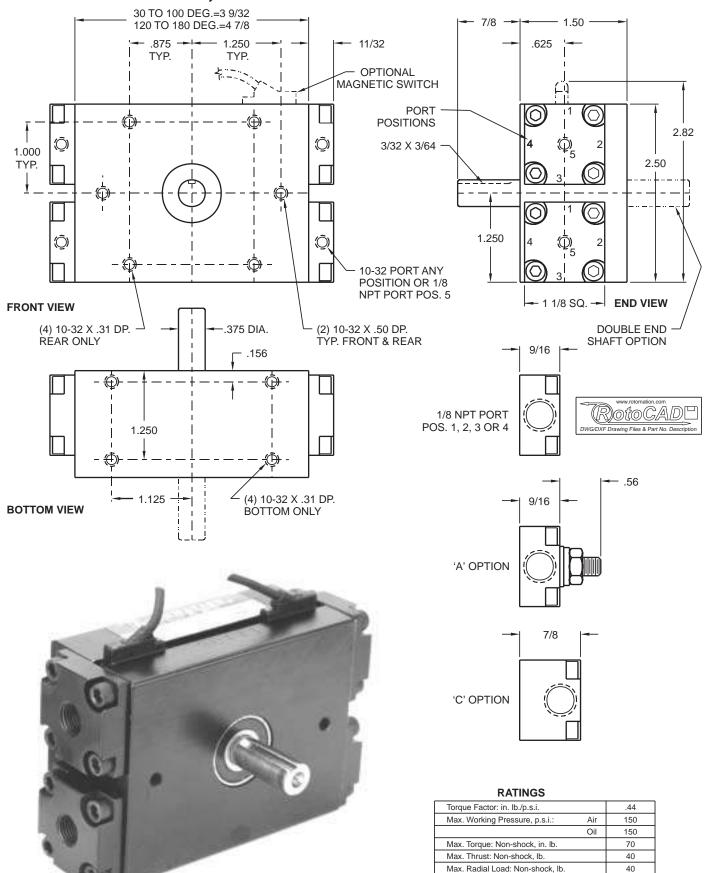
ORDER SEPARATELY					
CABLE	PART NUMBER				
2 METER LENGTH	CC2				
5 METER LENGTH	CC5				

SEAL REPAIR KITS PART NUMBERS FOR SEAL REPAIR KITS

FILL IN UNIT SERIES AND ALL RELATED OPTIONS: — C — A -SRK - A3 -· VT SERIES CUSHIONS ROTATION **SEALS ADJUSTERS** 

SEAL KIT FOR A752-180-TC-S37-2C1-1Q-2SL-2A-V-1/8-2 = SRK-A752-C-A NOTE: IF NO OPTIONS, SPECIFY SRK-A752-STD.

# A752 COMPACT, HIGH TORQUE DUAL RACK ACTUATOR

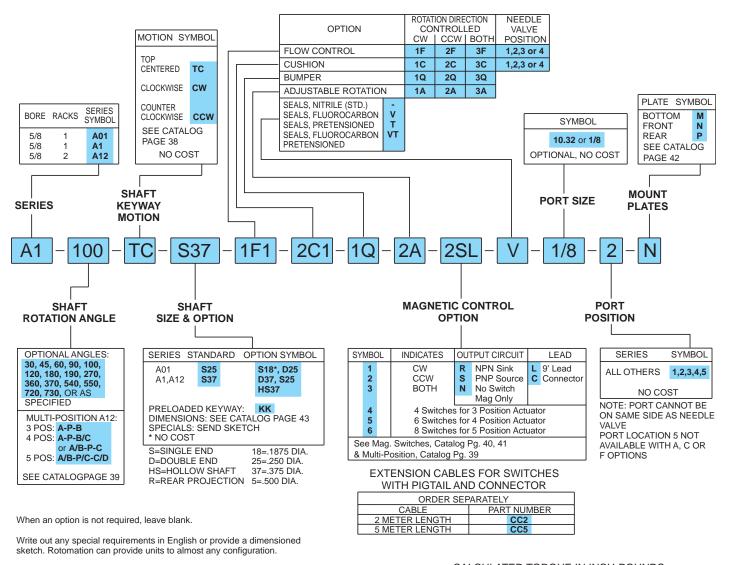


.0078

1.9

Displacement: in ³/deg.
Weight 180 deg. std. unit: lb.

# 



To expedite the order of a duplicate of a prior unit, refer to prior invoice/serial number stamped on the unit body.

Flow control and cushion cannot be installed in same end cap. Flow control in A01, A1, A12 10.32 port only.

Needle valve cannot be on same side as port.

# CALCULATED TORQUE IN INCH-POUNDS

Deduct 10% for friction

	OPERATING PRESSURE IN PSI						
UNIT	25	50	60	80	100	200	
A01	1.9	3.8	4.6	6.2	7.7	-	
A1	3.8	7.6	9.2	12.3	15.3	30.7	
A12	7.6	15.2	18.4	24.6	30.6	-	

# SEAL REPAIR KITS PART NUMBERS FOR SEAL REPAIR KITS

FILL IN UNIT SERIES AND ALL RELATED OPTIONS:

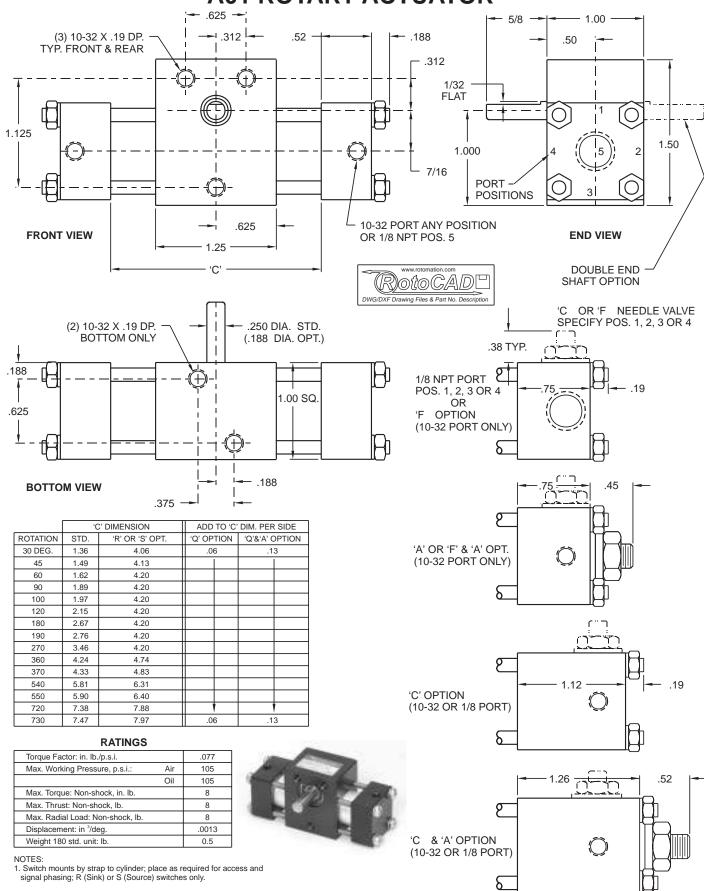


**EXAMPLES**:

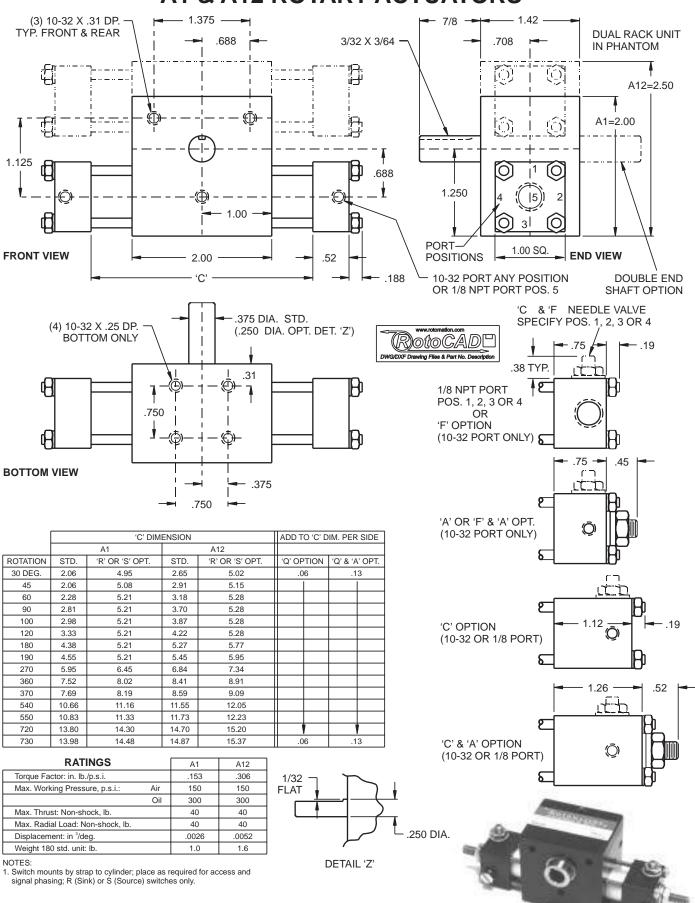
SEAL KIT FOR A12-90-0-90-S37-3F1-1/8-2 = SRK-A12-90-0-90-F

NOTE: IF NO OPTIONS, SPECIFY SRK-A12-STD.

# **A01 ROTARY ACTUATOR**



# **A1 & A12 ROTARY ACTUATORS**



# **BUILT FOR OEM - RIGHT MOTION - RIGHT SIZE**

### DO IT IN THREES



The "LOCK STEP ACTUATOR" drives three shafts in spooky synchronism. A42-360 triple shown.

### SAVE SPACE WITH HYBRID STEPPING ACTUATOR



Cramped for space (note necked down tie rods) but need lots of torque In washdown package. S3 drive cylinder, S2 reset cylinder. Symbol: written description

# **DOUBLE TORQUE, DOUBLE UNITS**



High torque in small package. Symbol: 44 S44-360-CW-S10-3C2-1/4-1,3 shown A special that has become popular.

### **OEM SPECIALS**

With just a few custom parts, units uniquely suited to process functions provide low cost means to efficient, reliable productions systems.

# **DOUBLE TORQUE - FIVE POSITIONS**



A44-90/45-0-90/45-HS75-1/4-1,3 SHOWN

### **CAPABLE AND TOUGH**



Three position A12: exposed parts electroless nickel plated or solid stainless steel.

### **CONCENTRIC SHAFT ACTUATORS**



Two actuators on same centerline. Concentric shafts independently driven.

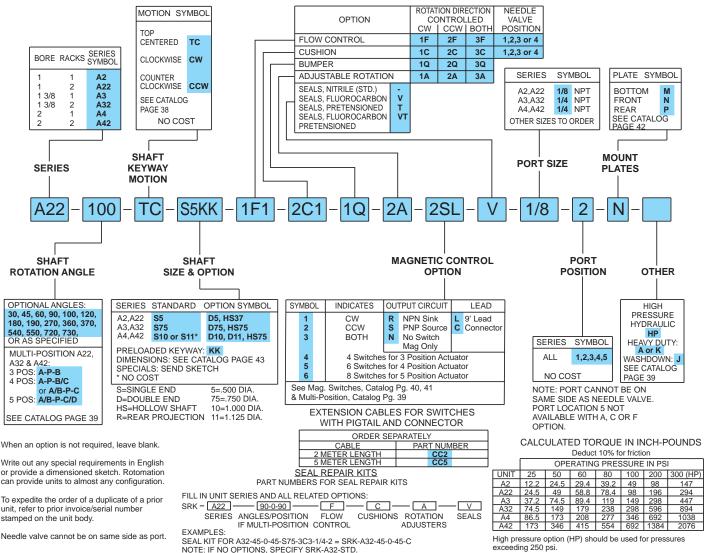
A2 and A4 shown.

# THREE POSITIONS-GENTLY



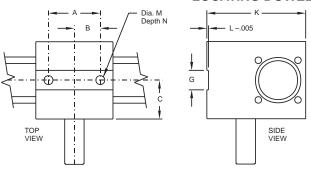
Moves fragile product to any of three positions. Smooth motion, progressive cushions with fine adjustment, shaft to fit load. A22 shown.

### CONTROL OF THE PROPERTY ACTUATOR ROTATION DIRECTION CONTROLLED NEEDLE MOTION SYMBOL OPTION VALVE



### LOCATING DOWEL PIN SOCKETS-TIE ROD UNITS

NOTE: IF NO OPTIONS, SPECIFY SRK-A32-STD.

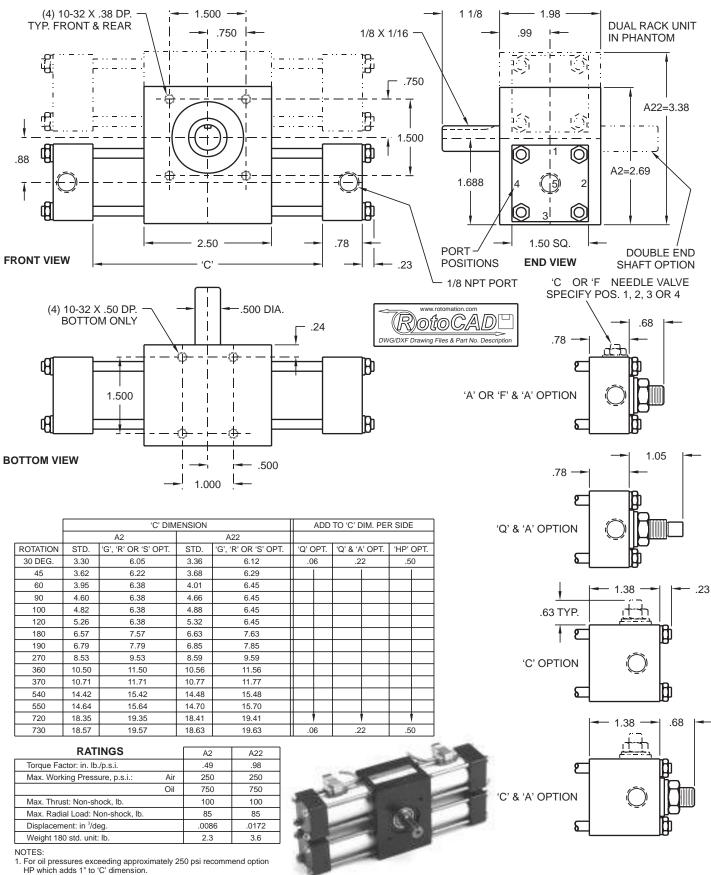


Initial and replacement unit installations can be made precisely using locating dowel pin sockets in Rotomation units.

Socket locations and dimensions are listed below for tie rod units. Note that sockets on unit top are in machine finished groove under Rotomation label.

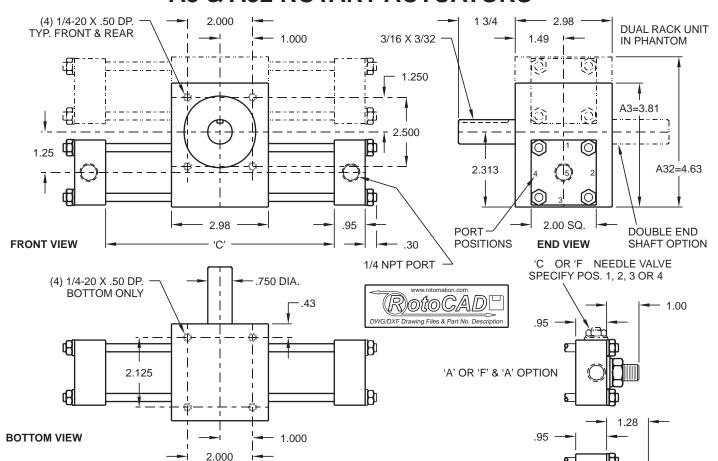
	UNIT	Α	В	С	D	Е	F	G	Н	J	K	L	М	N
	A01	-	-	-	.750	.375	.50	-	-	-	1.50	-	.125	.090
BOTTOM Dia. M	A1,S1	.750	.375	.708	.750	.375	.708	-	-	-	1.50	-	.188	.150
VIEW Depth N	X1	1.000	.500	1.311	1.000	.500	1.311	-	-	-	2.00	-	.188	.150
	A12,S12	.750	.375	.708	.750	.375	.708	-	-	-	2.50	-	.188	.150
	X12	1.000	.500	1.311	1.000	.500	1.311	-	-	-	2.50	-	.188	.150
	A2,S2	1.500	.750	.991	-	-	-	.750	1.500	.750	2.69	.030	.250	.200
<	X2	1.500	.750	1.500	1.500	.750	1.500	.750	-	-	2.69	.030	.250	.200
>	A22,S22	1.500	.750	.991	-	-	-	.750	1.500	.750	3.38	.030	.250	.200
	X22	1.500	.750	1.500	1.500	.750	1.500	.750	-	-	3.38	.030	.250	.200
'   i <del>Q i   ' ' '</del>	A3,S3,X3	1.375	.6875	1.490	1.563	.781	1.490	.750	-	-	3.81	.030	.375	.250
	A32,S32,X32	1.375	.6875		1.563	.781	1.490	.750	-	-	4.63	.030	.375	.250
; <del></del> : E <del>;</del> -	A4,S4,X4	1.375	.6875	1.490	2.000	1.000	1.490	.750	-	-	4.31	.030	.375	.250
<b>→</b> D <b>→</b>	A42,S42,X42	1.375	.6875	1.490	2.000	1.000	1.490	.750	-	-	5.50	.030	.375	.250

# **A2 & A22 ROTARY ACTUATORS**



<sup>2.</sup> Switch bracket mounts to tie rod; place as required for access and signal phasing.

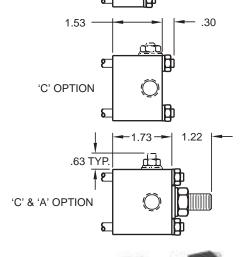
# A3 & A32 ROTARY ACTUATORS



	'C' DIMENSION					ADD	TO 'C' D	IM. PEF	SIDE	
	A3 A32									
ROTATION	STD.	'G', 'R' OR 'S' OPT.	STD.	'G', 'R' OR 'S' OPT.	'Q' (	OPT.	'Q' & 'A	' OPT.	'HP'	OPT.
30 DEG.	4.44	6.63	4.50	6.70	.0	6	.2	9	.5	0
45	4.96	6.90	5.02	6.97						
60	5.49	7.16	5.55	7.23						
90	6.53	7.53	6.59	7.59						
100	6.88	7.88	6.94	7.94						
120	7.58	8.58	7.64	8.64						
180	9.68	10.68	9.74	10.74						
190	10.03	11.03	10.09	11.09						
270	12.82	13.82	12.88	13.88						
360	15.96	16.96	16.02	17.02						
370	16.31	17.31	16.37	17.37						
540	22.24	23.24	22.30	23.30						
550	22.59	23.59	22.65	23.65						
720	28.53	29.53	28.59	29.59		1	,	1	1	1
730	28.87	29.87	28.93	29.93	.0	6	.2	9	.5	0

RATINGS		A3	A32
Torque Factor: in. lb./p.s.i.		1.49	2.98
Max. Working Pressure, p.s.i.:	Air	250	250
	Oil	750	750
Max. Thrust: Non-shock, lb.		300	300
Max. Radial Load: Non-shock, lb.		300	300
Displacement: in <sup>3</sup> /deg.		.026	.052
Weight 180 std. unit: lb.		6.1	8.8

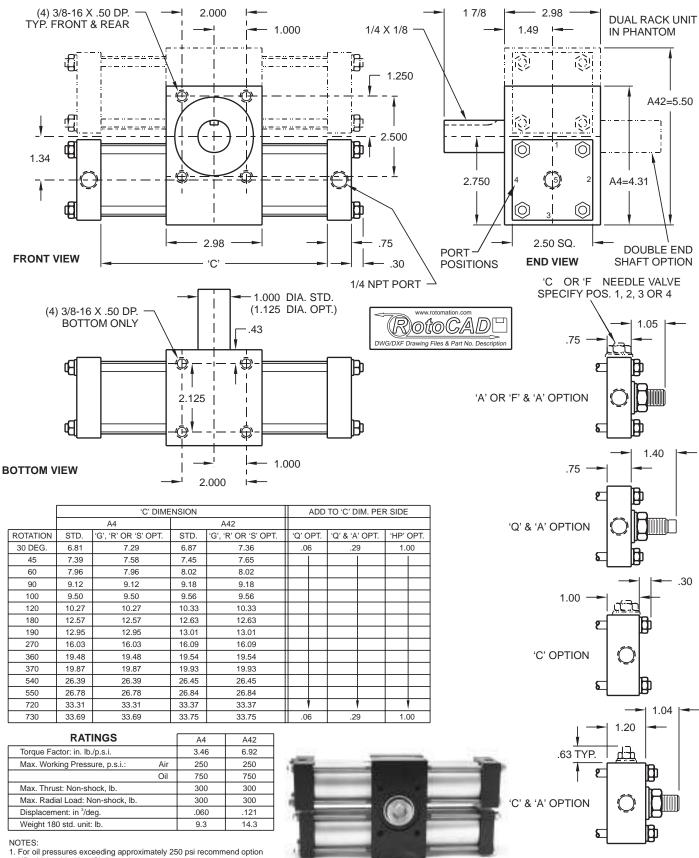
- NOTES: 1. For oil pressures exceeding approximately 250 psi recommend option HP which adds 1" to 'C' dimension.
- Switch mounts by strap to cylinder; place as required for access and signal phasing.



'Q' & 'A' OPTION



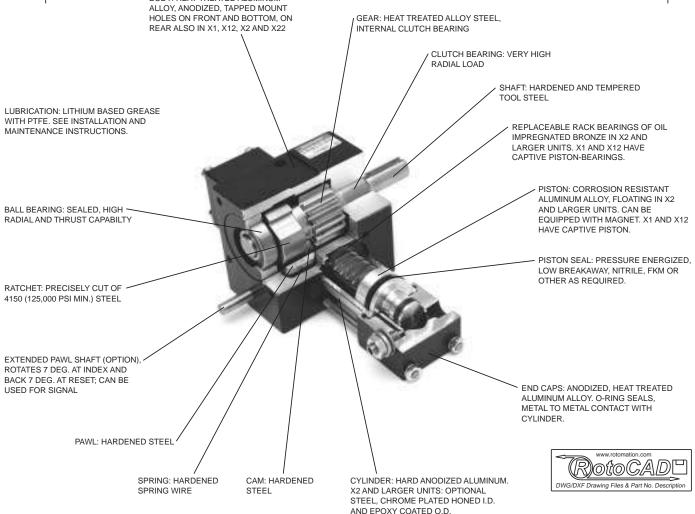
# **A4 & A42 ROTARY ACTUATORS**



- For oil pressures exceeding approximately 250 psi recommend option HP which adds 2" to 'C' dimension.
   Switch bracket mounts to tie rod; place as required for access and
- Switch bracket mounts to tie rod; place as required for access and signal phasing.

# ONE STEP AT A TIME: THE INDEXING ACTUATOR





### **CONSTRUCTION AND OPERATION**

Construction and external size similar to rack and pinion actuator, but pinion drives shaft one way through overrunning clutch.

Four way valve controls full cycle

Drive: Rack drives pinion, pinion drives shaft through overrunning clutch until pawl stops and locks ratchet.

Lock: Pawl prevents forward motion, rack force and non-return clutch prevent reverse motion.

Reset: Rack reverses, drives pinion backward to start point, cam lifts pawl; shaft remains stationary held by non-return clutch. Each shaft step controlled by accurately cut ratchet.

Sensors and system signals

Extended pawl shaft moves 7 deg. at index and reset; use proximity detector, low force sensitive switch or pilot valve Magnetic pistons and switches

Shaft Motion

Angular step accuracy: 0.2 degree

No cumulative error

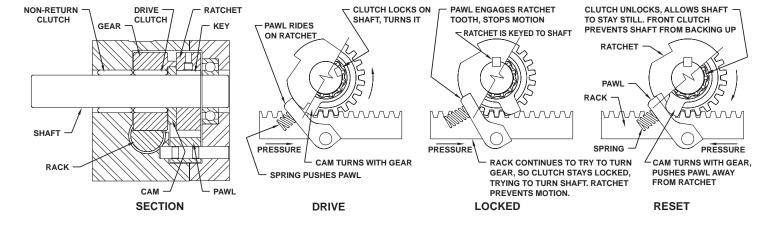
Shaft locked in both directions in index position at end of drive stroke
Stop at end of drive stroke is abrupt; avoid shock by flow control of
exhausting cylinder to limit velocity

Drive is through overrunning clutch; cushion on drive cylinder ineffective without friction in load

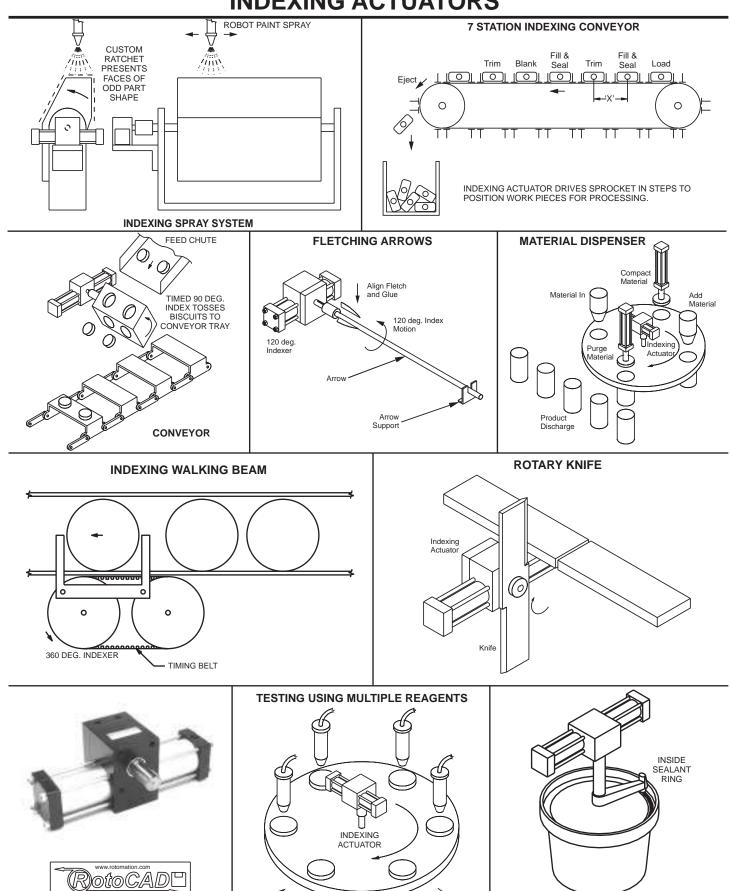
Shaft movable in forward direction by outside torque in reset

No reverse shaft motion: Non-return clutch

Reset operation quick, moves only pistons, rack, pinion, cam pawl. Silence with cushion if desired.



# APPLICATIONS-POSSIBLE ONLY WITH ROTOMATION INDEXING ACTUATORS



UNLOAD

**DISPENSE ADHESIVE** 

LOAD



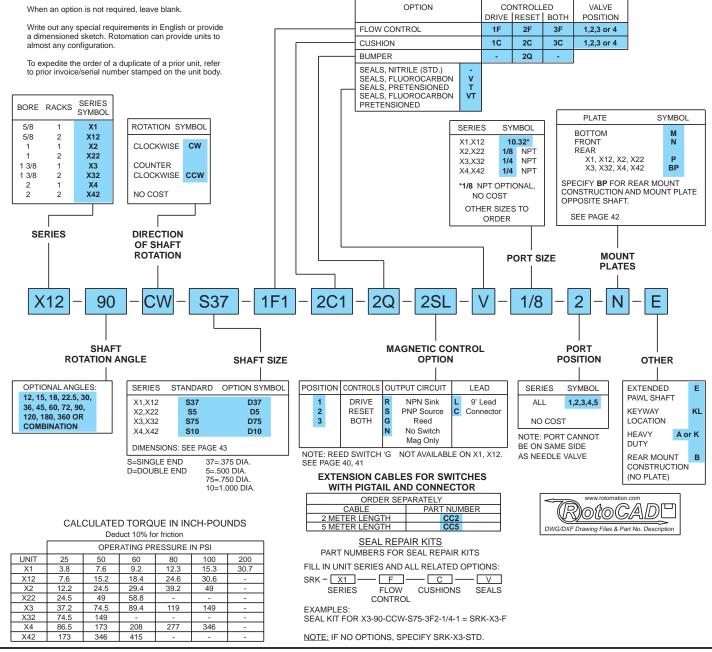
# **DESIGN YOUR INDEXING ACTUATOR**





NEEDLE

OPERATION



Mechanical signal of index and reset. Sense with switch, pilot valve or proximity detector.

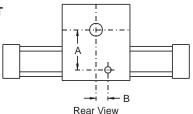
Pawl and shaft move 7; at index and reset; cam driven at reset, spring driven at index. Use 1" arm, proximity detector or sensitive switch.

Shaft projects 3/4" from back of body. See page 41.

Symbol: E X3-120-CCW-S75-1F12C1-2E shown.

NOTE that magnetic pistons and switches may also be used on the indexer.





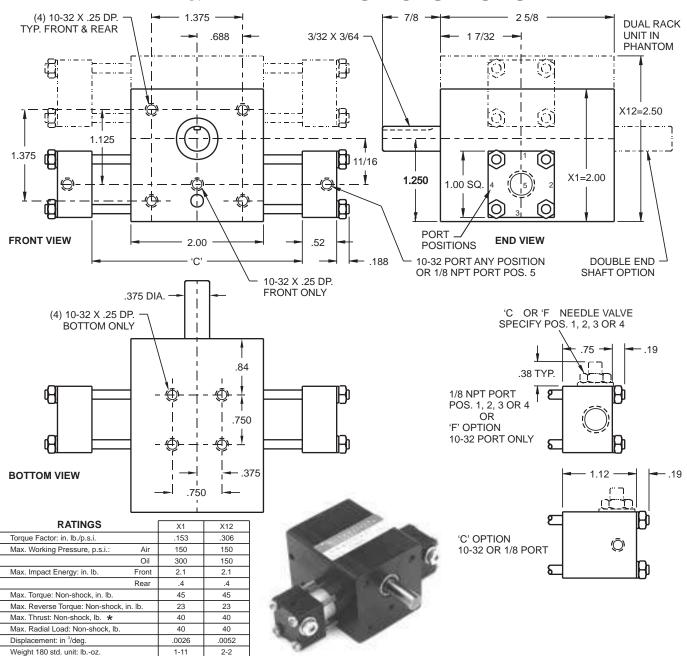
UNIT	SHAFT	DIM. A	рім. в	PAWL SHAFT	ROTATION
UNIT	DIA.	DIIVI. A	DIIVI. B	DRIVE	RESET
X1 CW	.188	.936	0	CW	CCW
X1 CCW	.188	.936	0	CCW	CW
X2 CW	.250	1.309	+.107	CW	CCW
X2 CCW	.250	1.309	107	CCW	CW
X3 CW	.375	1.875	0	CW	CCW
X3 CCW	.375	1.875	0	CCW	CW
X4 CW	.375	2.201	+.188	CW	CCW
X4 CCW	.375	2.201	188	CCW	CW

DAME CLIAFT DOTATION

<sup>+</sup> to right of centerline

<sup>-</sup> to left of centerline

# X1 & X12 INDEXING ACTUATORS



* -Thrust inward, front to rear only. Do not app	bly thrust in opposite direction.

	'C' DIMENSION			ADD TO 'C' RESET SIDE	
		X1		X12	
ROTATION	STD.	'R' OR 'S' OPT.	STD.	'R' OR 'S' OPT.	'Q' OPT.
12 DEG.	2.06	4.79	2.06	4.79	.06
15	2.06	4.81	2.06	4.81	
18	2.06	4.84	2.06	4.84	
22.5	2.06	4.88	2.06	4.88	
30	2.06	4.95	2.06	4.95	
36	2.06	5.00	2.06	5.00	
45	2.06	5.08	2.06	5.08	
60	2.31	5.21	2.30	5.21	
72	2.52	5.21	2.51	5.21	
90	2.84	5.21	2.83	5.21	
120	3.36	5.21	3.35	5.21	
180	4.41	5.21	4.40	5.21	1
360	7.55	8.05	7.54	8.04	.06

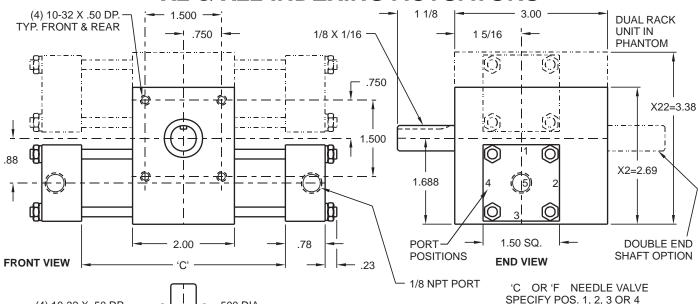
- 1. An uncontrolled reset stroke can cause some bounce of the rack and a small forward impulse to the 1. An information reset stoke can cause some bounce on the fact, and a small nimbuse to the shaft. It will be apparent only if the shaft load is small, with low friction. It can be reduced by a bumper (usable on reset cylinder only) or more by a correctly adjusted cushion.

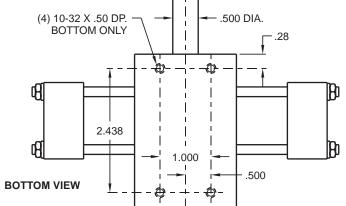
  2. Switch mounts by strap to cylinder; place as required for access and signal phasing; R (Sink) or S (Source) switches only.

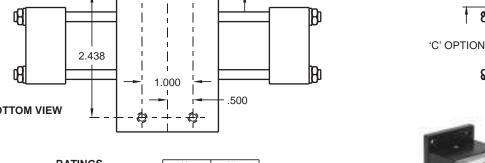
### INDEXING ACCURACY -0.2 deg. **SHAFT KEYWAY POSITION** Reference (start) position of shaft keyway: 30; indexer 11:30 345i 270i 60; indexer 9:00 120; indexer 6:00 180i 12:00 All others 0i (Angles measured with respect to bottom of body.) Accuracy of reference position -2i Optional high accuracy reference position (not available on 15, 18 and 22.5 deg. units) -0.2i Symbol: KI



# X2 & X22 INDEXING ACTUATORS







RATINGS	X2	X22
		^22
Torque Factor: in. lb./p.s.i.	.49	.98
Max. Working Pressure, p.s.i.:	Air 150	75
	Oil 150	75
Max. Impact Energy: in. lb. Fr	ont 4	4
R	ear 1.2	1.2
Max. Torque: Non-shock, in. lb.	73	73
Max. Reverse Torque: Non-shock, in. lb	. 37	37
Max. Thrust: Non-shock, lb. *	50	50
Max. Radial Load: Non-shock, lb.	70	70
Displacement: in ³/deg.	.0086	.0172
Weight 180 deg. std. unit: lboz.	2-15	4-8

★ -Thrust inward, front to rear only. Do not apply thrust in opposite direction.

	'C' DIMENSION			ADD TO 'C' RESET SIDE	
		X2		X22	
ROTATION	STD.	'G', 'R' OR 'S' OPT.	STD.	'G', 'R' OR 'S' OPT.	'Q' OPT.
12 DEG.	2.90	5.36	2.89	5.36	.06
15	2.97	5.39	2.96	5.39	
18	3.03	5.42	3.02	5.42	
22.5	3.13	5.47	3.12	5.47	
30	3.29	5.55	3.28	5.55	
36	3.43	5.62	3.42	5.62	
45	3.62	5.72	3.61	5.72	
60	3.95	5.88	3.94	5.88	
72	4.21	5.88	4.20	5.88	
90	4.60	5.88	4.59	5.88	
120	5.26	6.26	5.25	6.25	
180	6.57	7.57	6.56	7.56	
360	10.49	11.49	10.48	11.48	.06

### NOTES:



.63

SHOWN WITH OPTIONAL MOUNT PLATE

INDEXING	ACCURACY -0.2	deg.			
SHAFT	SHAFT KEYWAY POSITION				
Reference (start) position of	of shaft keyway:				
30; indexer	11:30	345 <sub>i</sub>			
60; indexer	9:00	270 <sub>i</sub>			
120; indexer	6:00	180 <sub>i</sub>			
All others	12:00	0 <sub>i</sub>			
(Angles measured with res	(Angles measured with respect to bottom of body.)				
Accuracy of reference pos	ition	-2 <sub>i</sub>			
Optional high accuracy reference position					
(not available on 15, 18 an Symbol: KL	d 22.5 deg. units)	-0.2 <sub>i</sub>			

1.38

The state of

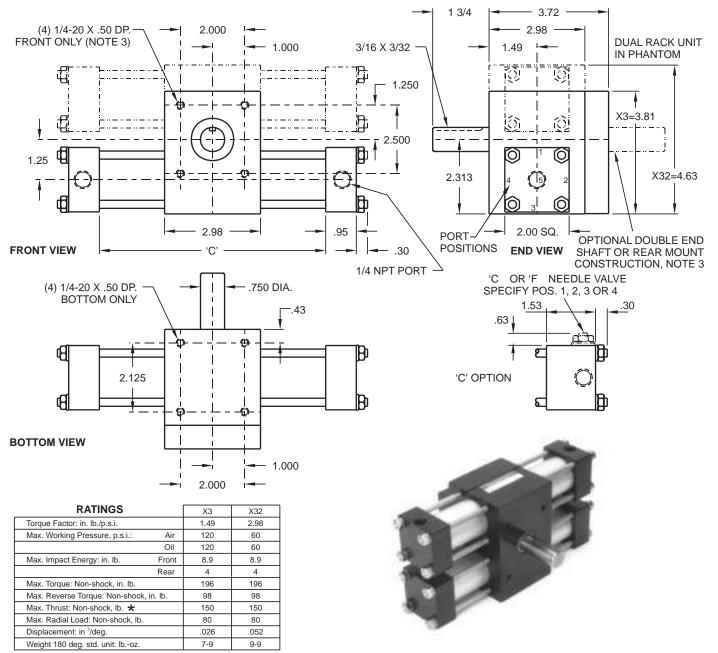
- .23



<sup>1.</sup> An uncontrolled reset stroke can cause some bounce of the rack and a small forward impulse to the shaft. It will be apparent only if the shaft load is small, with low friction. It can be reduced by a bumper (usable on the reset cylinder only) or more by a correctly adjusted cushion.

<sup>2.</sup> Switch bracket mounts to tie rod; place as required for access and signal phasing.

# X3 & X32 INDEXING ACTUATORS



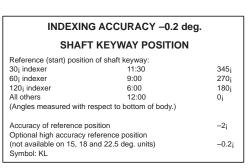
 $<sup>\</sup>bigstar$  -Thrust inward, front to rear only. Do not apply thrust in opposite direction.

1		'C' DIMENSION			ADD TO 'C' RESET SIDE
		X3		X32	NED TO CHECK OID
ROTATION	STD.	'G', 'R' OR 'S' OPT.	STD.	'G', 'R' OR 'S' OPT.	'Q' OPT.
12 DEG.	4.31	6.32	4.30	6.32	.06
15	4.41	6.37	4.40	6.37	
18	4.52	6.42	4.51	6.42	
22.5	4.68	6.50	4.67	6.50	
30	4.94	6.63	4.93	6.63	
36	5.15	6.74	5.14	6.74	
45	5.46	6.90	5.45	6.90	
60	5.99	7.16	5.98	7.16	
72	6.40	7.40	6.39	7.39	
90	7.03	8.03	7.02	8.02	
120	8.08	9.08	8.07	9.07	
180	10.17	11.17	10.16	11.16	1
360	16.46	17.46	16.45	17.45	.06

### NOTES

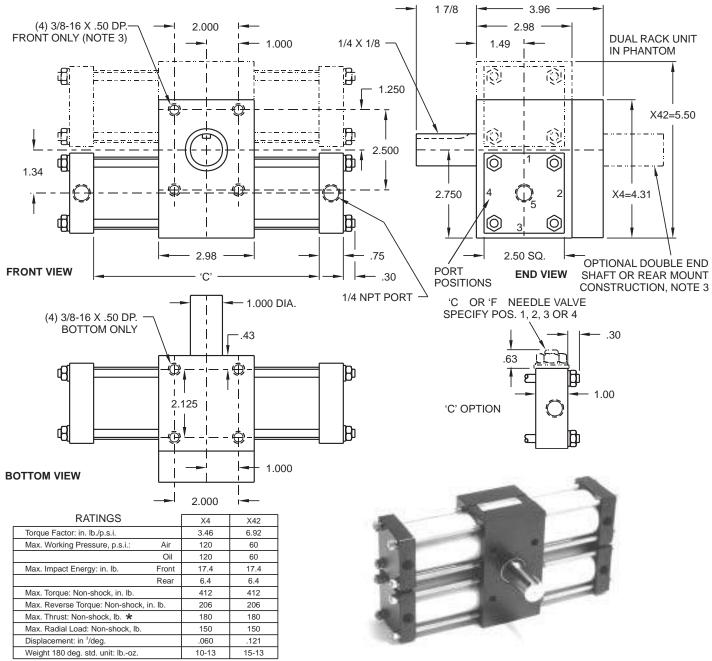
- 1. An uncontrolled reset stroke can cause some bounce of the rack and a small forward impulse to the shaft. It will be apparent only if the shaft load is small, with low friction. It can be reduced by a humber (usable on the reset cylinder only) or more by a correctly adjusted cushion.
- bumper (usable on the reset cylinder only) or more by a correctly adjusted cushion.

  2. Switch mounts by strap to cylinder; place as required for access and signal phasing.
- For rear mount, order rear mount construction to reverse body and provide rear mount holes. Note reduced impact energy capacity, page 29.





# X4 & X42 INDEXING ACTUATORS



*	-Thrust inward,	front to rear	only. Do	not apply	thrust in	opposite	direction.
---	-----------------	---------------	----------	-----------	-----------	----------	------------

	,		, ,	-11	
	'C' DIMENSION			ADD TO 'C' RESET SIDE	
		X4		X42	
ROTATION	STD.	'G', 'R' OR 'S' OPT.	STD.	'G', 'R' OR 'S' OPT.	'Q' OPT.
12 DEG.	6.20	6.94	6.19	6.94	.06
15	6.31	7.00	6.30	7.00	
18	6.43	7.06	6.42	7.06	
22.5	6.60	7.14	6.59	7.14	
30	6.89	7.29	6.88	7.29	
36	7.12	7.40	7.11	7.40	
45	7.46	7.58	7.45	7.58	
60	8.04	8.04	8.03	8.03	
72	8.50	8.50	8.49	8.49	
90	9.19	9.19	9.18	9.18	
120	10.34	10.34	10.33	10.33	
180	12.65	12.65	12.64	12.64	<b>†</b>
360	19.56	19.56	19.55	19 55	06

### NOTES:

- 1. An uncontrolled reset stroke can cause some bounce of the rack and a small forward impulse to the shaft. It will be apparent only if the shaft load is small, with low friction. It can be reduced by a bumper (usable on the reset cylinder only) or more by a correctly adjusted cushion.
- Switch bracket mounts to tie rod, place as required for access and signal phasing.
   For rear mount, order rear mount construction to reverse body and provide rear mount holes. Note reduced impact energy capacity, page 29.

INDEXING ACCURACY -0.2 deg.				
SHAFT KEYWAY POSITION				
Reference (start) positio	n of shaft keyway:			
30; indexer	11:30	345 <sub>i</sub>		
60; indexer	9:00	270i		
120; indexer	6:00	180 <sub>i</sub>		
All others	12:00	0 <sub>i</sub>		
(Angles measured with respect to bottom of body.)				
Accuracy of reference position -2i				
Optional high accuracy reference position				
(not available on 15, 18 Symbol: KL	and 22.5 deg. units)	-0.2 <sub>i</sub>		

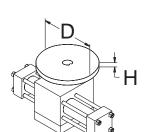


# INDEXING SIMPLIFIED: CALCULATE IMPACT EASILY

Impact can displace work pieces, damage fixtures or the indexing actuator itself by breaking its shaft or ratchet key.

Avoid these effects by limiting rotational speed with a flow control; use the maximum available time consistent with cycle requirements.

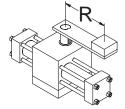
### **CALCULATE MOMENT OF INERTIA**



D = diameter
H = thickness, in
D = density, lb/in<sup>3</sup>
M = weight, lb
R = radius, in
L = length, in
A = width, in

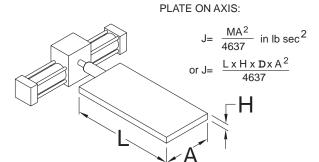
DISC:

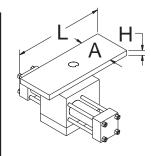
$$J = \frac{D^4 \pi H D}{12365} \text{ in lb sec}^2$$
or  $J = \frac{MD^2}{D}$ 



CONCENTRATED LOAD:

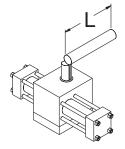
$$J = \frac{MR^2}{386.4} \text{ in lb sec}^2$$





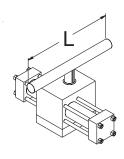
**RECTANGULAR PLATE:** 

$$J = \frac{M(L^2 + A^2)}{4637} \text{ in lb sec}^2$$
or  $J = \frac{AHLD (L^2 + A^2)}{4637}$ 



THIN ROD AROUND ONE END:

$$J= \frac{ML^2}{1159} \text{ in lb sec}^2$$



THIN ROD AROUND CENTER:

$$J= \frac{ML^2}{4637} \text{ in lb sec}^2$$

### **CALCULATE IMPACT IN ROTARY MOTION**

 $\theta$  = angle of motion in radians, 1 radian = 57.3 degrees

w = angular velocity in radians/second

t = time duration of motion in seconds

For many pneumatic systems

 $\mathbf{W} = 2.3 \times \theta / t$  gives a reasonable estimate of maximum angular velocity

Impact energy:

W = impact energy in in lb

J = total moment of inertia of entire shaft load in in lb  $sec^2$ 

= J of workpiece + J of fixtures + J of supports member(s)

 $W = 1/2Jw^{2}$ 

### **UNIT SELECTION**

The following are maximum practical values of W for production use. They are based upon shaft tests to failure and provide a factor of safety of about 4 for shaft fracture. Though safe for the shaft, this impact may dislodge product or have other inertia effects.

UNIT	FRONT SHAFT	<b>REAR SHAFT</b>
X1 & X12	2.1 in lb	.4 in lb
X2 & X22	4	1.2
X3 & X32	8.9	4
X4 & X42	17.4	6.4

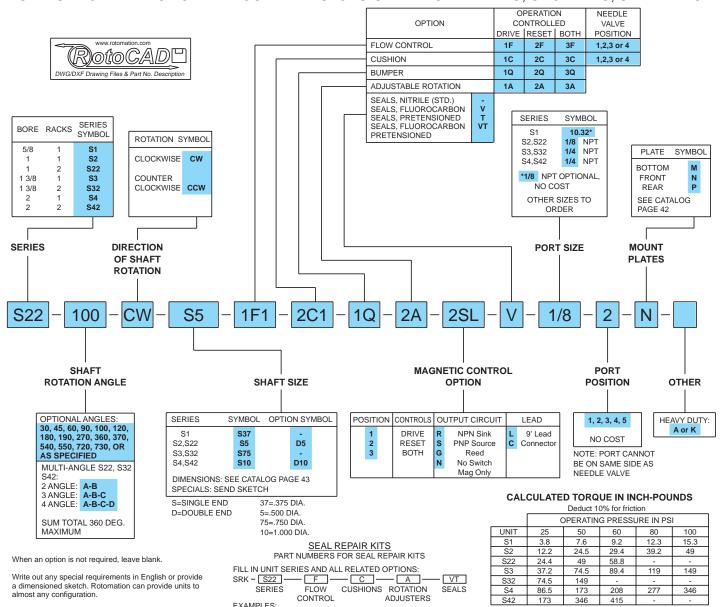




# **DESIGN YOUR STEPPING ACTUATOR**



STEPS IN ONE DIRECTION WITHOUT HARD STOPS-GREAT FOR FEEDING, CROWDING, SPREADING



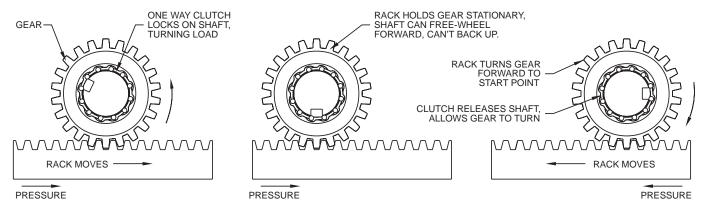
To expedite the order of a duplicate of a prior unit, refer to prior invoice/serial number stamped on the unit body.

Flow control and cushion cannot be installed in same end cap. Flow control in S1 10.32 port only.

### STEPPING ACTUATOR OPERATION

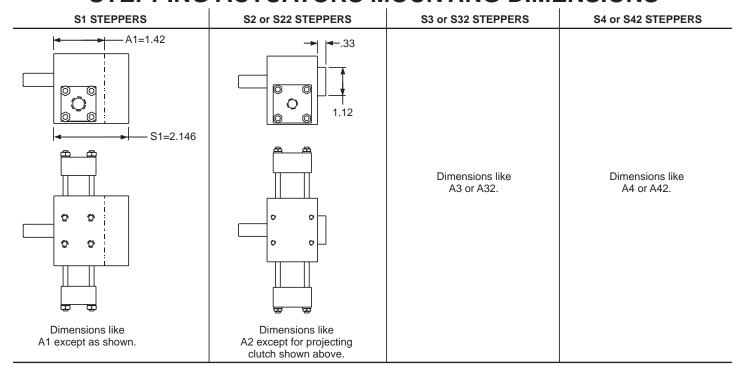
SEAL KIT FOR \$2-90-CW-\$5-1F2-2A-V-1/8-1 = \$RK-\$2-F-A-V

NOTE: IF NO OPTIONS, SPECIFY SRK-S22-STD.



DRIVE END OF DRIVE STROKE RESET

# STEPPING ACTUATORS MOUNTING DIMENSIONS



### STEPPING ACTUATOR RATINGS

	S1	S2	S22	S3	S32	S4	S42
Torque Factor: in. lb./p.s.i.	.153	.49	.98	1.49	2.98	3.46	6.92
Max. Working Pressure, p.s.i.: Air	150	150	75	130	65	120	60
Oil	300	150	75	130	65	120	60
Max. Torque: Non-shock, in. lb.	45	73	73	196	196	412	412
Max. Reverse Torque: Non-shock, in. lb.	23	37	37	98	98	206	206
Max. Thrust: Non-shock, lb.	40	75	75	150	150	200	200
Max. Radial Load: Non-shock, lb.	40	75	75	150	150	200	200
Displacement: in ³/deg.	.0026	.0086	.0172	.026	.052	.060	.121
Weight 180 deg. std. unit: lboz.	1-2	2-7	3-12	6-2	8-12	8-14	13-14



## HINTS ON USING A STEPPING ACTUATOR

The stepping actuator provides torque while rotating through its specified angle, always in one direction. It has no ability to slow or stop its load, so it will stop at a point determined by load inertia, friction, or external stops. The shaft can freewheel in the forward direction without restriction, so it has no fixed reference position. A one way clutch in the body prevents rotation in the reverse direction. Optional rotation adjusters can be used to set the stroke, and multiple stroke lengths can be obtained from a multi-angle actuator. The actuator can be stalled continuously by an external stop without problems.

Natural applications for the stepping actuator include:

indexing applications where there is a high drag/inertia ratio and where error does not accumulate, such as driving a pinch roller to pull stock from a spool incrementally to be cut into lengths

driving detented items such as rotary switches, cam sequences, etc

those needing one-direction rotary motion with no position accuracy requirement, such as waste conveyors

### Torque Ratings

The maximum torque is limited by the roller clutches used to drive the shaft and to prevent reverse rotation. Exceeding the maximum working pressure specified may overload the clutch, reducing life and/or causing immediate failure. Dual rack actuators are intended for use in applications where the maximum torque rating of the clutch cannot be utilized on normal shop air. Please note that normal shop air may overload the clutch on a dual rack actuator.

Reverse torque from an external source can also damage the actuator if it exceeds the maximum torque rating.

### PRECISE POSITIONING/INDEXING

The stepping actuator can index even a high inertia load very precisely with a shot pin or other detent mechanism. The precision of the angle and load position is that of the detent system. This offers a number of advantages:

The stop positions can be adjusted by adjustment of the detent position.

Irregular, custom angle sequences are possible.

The detent can be placed at a large radius to handle high inertia loads.

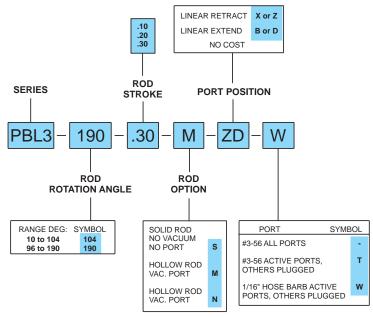
### LOAD POSITION STABILITY

The shaft and load are prevented from rearward motion by the drive clutch and by a similar non-return clutch installed between the shaft and body. However, the clutches offer no resistance to forward motion, so torques in that direction will displace the shaft and load. Unwanted forward motion can be prevented by a controlled clutch/brake. Such a device can be installed on the rear projection of a double ended shaft.

# CONTROL DESIGN YOUR PBL3 PICK & PLACE ACTUATOR CONTROL



# MINIATURE-VACUUM THRU ROD-BUILT IN VACUUM PORT

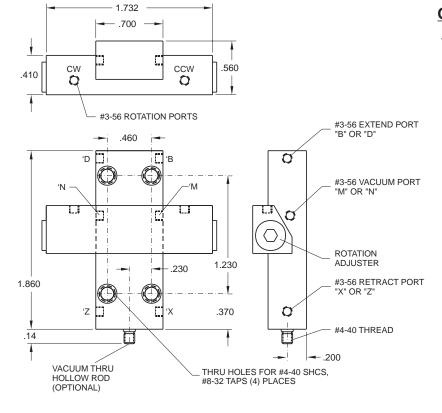


# MAXIMUM RATINGS

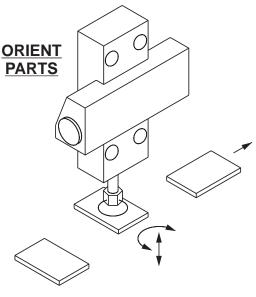
Pressure PSI	Torque In. Lb.	Push Lb.	Pull Lb.
20	.09	1.0	0.7
40	.18	1.9	1.4
60	.27	2.9	2.2
80	.36	3.9	2.9
100	.45	4.9	3.6

**OPERATION** 

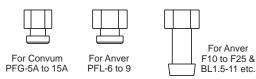
	-		
Rotary Section-Max. Pressure Air		100 PSI	
Linear Section-Max. Pres	Linear Section-Max. Pressure Air		
Torque		.45 In. Lb.	
Rotary Actuator Disp.	.008 Cu.	In. /94 Deg.	
Weight	_	1.6 Oz.	





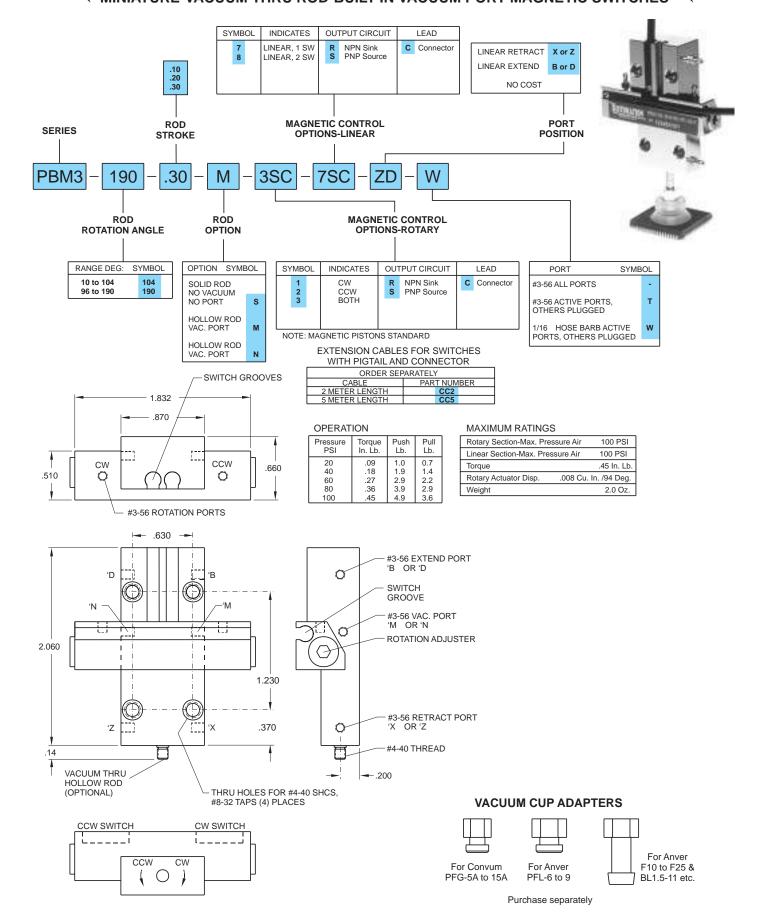


# **VACUUM CUP ADAPTERS**



Purchase separately

# DESIGN YOUR PBM3 PICK & PLACE ACTUATOR MINIATURE-VACUUM THRU ROD-BUILT IN VACUUM PORT-MAGNETIC SWITCHES



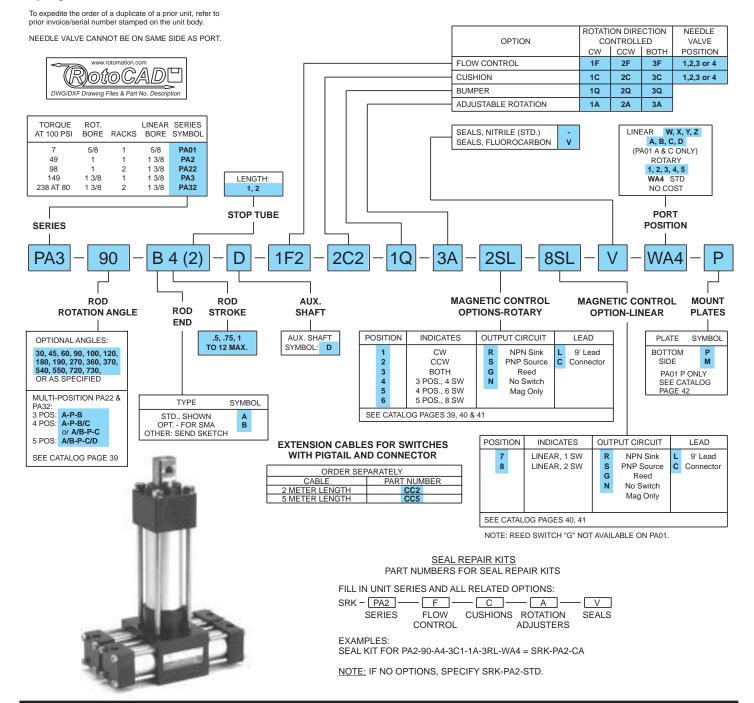


# DESIGN YOUR PICK & PLACE ACTUATOR 🔨



When an option is not required, leave blank

Write out any special requirements in English or provide a dimensioned sketch. Rotomation can provide units to almost any configuration.





# DESIGN YOUR NITPICKER (INDEXING PICK & PLACE)

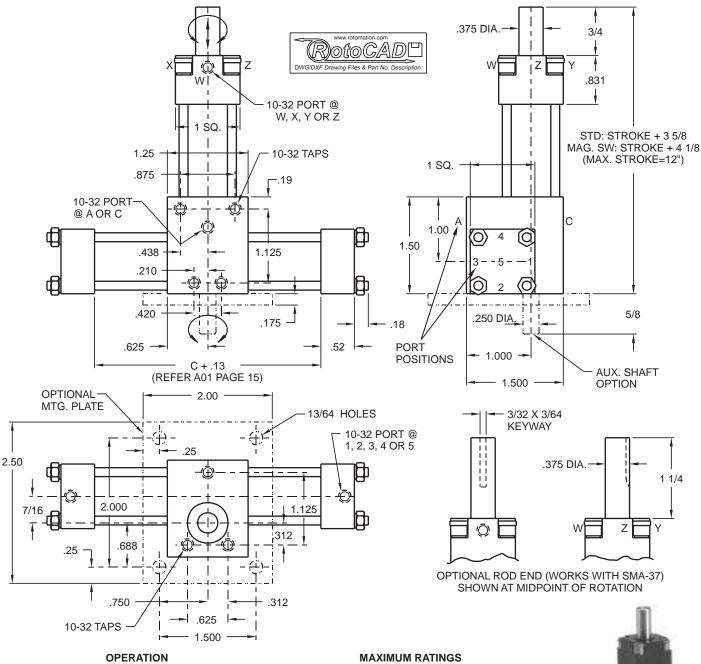


TO PROVIDE AN INDEXING ROTARY MOTION COMBINED WITH A LINEAR MOTION, CONSIDER THE NITPICKER. WHICH COMBINES THE X2 OR X22 ROTARY DRIVE WITH THE LINEAR MOTION FACILITY OF THE PA2 OR PA22.

CONFIGURATION IS SIMILAR TO THE PA2 OR PA22. FOR SPECIFICATION AND ORDERING DETAILS, CONSULT FACTORY; ASK FOR THE NITPICKER DESIGN CHART. FUNCTIONS AND OPTIONS ARE SIMILAR TO THOSE OUTLINED ABOVE BUT HAVE ROTARY CHARACTERISTICS OF THE X2 AND X22.

# PA01 MINIATURE PICK & PLACE ACTUATOR

LOTS OF ACTION, TINY SPACE, TINY COST



PRESSURE	TORQUE-IN. LB.	PUSH LB.	PULL LB.			
PSI	(.07 X PSI)	(.3 X PSI)	(.19 X PSI)			
60	4	18	11			
80	5	24	15			
100	7	30	19			

Above figures are computed; output torques and forces are reduced by internal friction.

UNCONTROLLED IMPACT CAN CAUSE DAMAGE. LIMIT BOTH ROTATIONAL & LINEAR SPEEDS BY USE OF FLOW CONTROL IN EXHAUSTING CYLINDER.

# **MAGNETIC SWITCH OPTIONS**

Solid state switches (R or S) are available on rotary and linear sections of unit. Switches mount to cylinders; place as required for access and phasing. Add 1/2" to cylinder length and unit height for linear switches.

ROTARY	PRESSURE, AIR	100		
SECTION	PRESSURE, OIL	100		
LINEAR	PRESSURE, AIR	100		
SECTION	PRESSURE, OIL	100		
TORQUE,	8			
Rot. Act. D	.0013			
Weight 180	0.9			

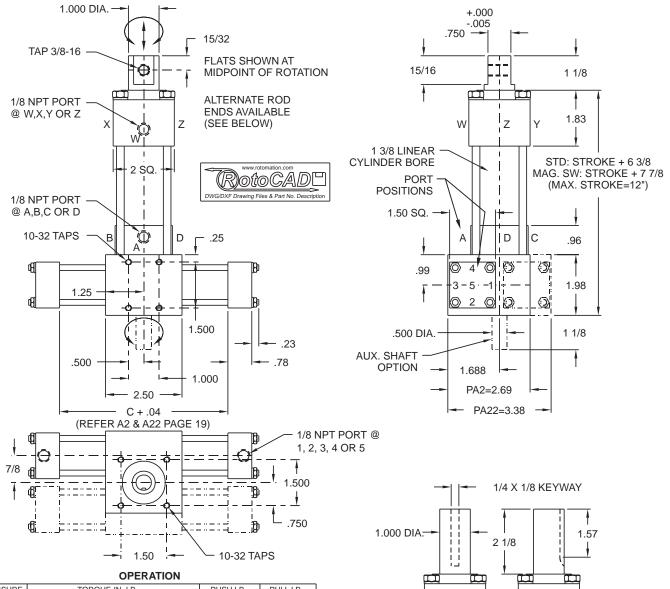
Rotation Tolerance: -0 +10 deg.

Backlash: 6 deg.

- NOTES:
  1. Rotary options available are the same as A01.
- Stop tubes are available to stabilize the extended shaft. Standard lengths are 1" and 2"; add to unit height. Sleeves for switch magnets serve the same function.
- 3. Needle valve: see page 15.



# PA2 & PA22 PICK & PLACE ACTUATORS



PRESSURE	TORQUE-IN. LB.		PUSH LB.	PULL LB.
PSI	PA2 (.49 X PSI)	PA22 (.98 X PSI)	(1.48 X PSI)	(.70 X PSI)
60	29	58	89	42
80	39	78	118	56
100	49	98	148	70
150	73	147	222	105
200	98	196	296	140
300	NA	NA	444	210
500	NA	NA	740	350

Above figures are computed; output torques and forces are reduced by internal friction.

### UNCONTROLLED IMPACT CAN CAUSE DAMAGE. LIMIT BOTH ROTATIONAL & LINEAR SPEEDS BY USE OF FLOW CONTROL IN EXHAUSTING CYLINDER.

# MAGNETIC SWITCH OPTIONS

Reed (G) and solid state switches (R or S) are available on rotary and linear sections of unit. Switches mount to cylinders; place as required for access and phasing.

### **ROTARY INSTALLATIONS:**

Find C dimension in tables on A2 & A22 page.

### LINEAR INSTALLATIONS:

Add 1 1/2" to cylinder length and unit height

# OPTIONAL ROD END (WORKS WITH SMA-10) SHOWN AT MIDPOINT OF ROTATION

W

Ζ

# MAXIMUM RATINGS

		PA2	PA22
ROTARY	PRESSURE, AIR	250	250
SECTION	PRESSURE, OIL	250	250
LINEAR	PRESSURE, AIR	250	250
SECTION	PRESSURE, OIL	500	500
TORQUE,	NON-SHOCK, INLB.	200	250
Rot. Act. D	Rot. Act. Disp: in ³/deg.		.0172
Weight 18	0 dea., 2" std. unit: lb.	5.4	6.7

Rotation Tolerance:

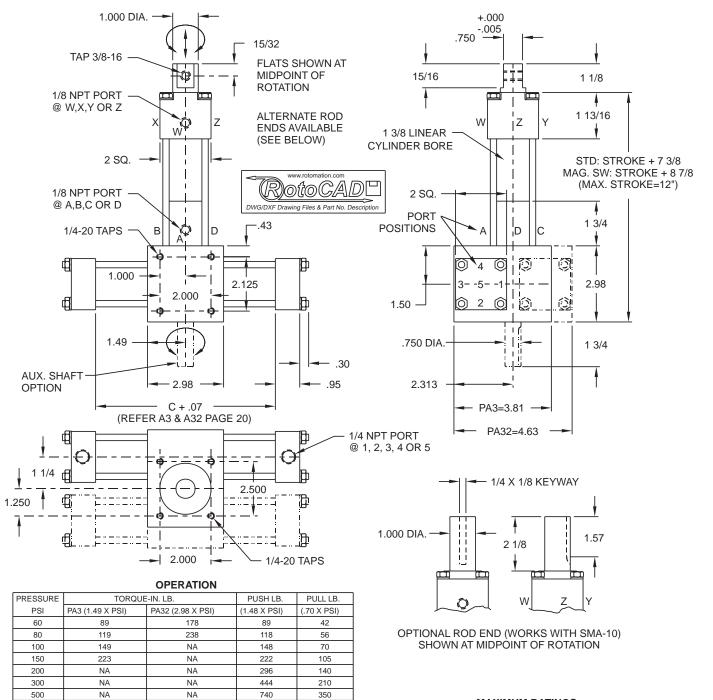
PA2 & PA22 -0 +3 deg.

Backlash:
PA2 2 deg.
PA22 1 deg.

### IOTES:

- Stop tubes are available to stabilize the extended shaft. Standard lengths are 1" and 2"; add to unit height. Sleeves for switch magnets serve the same function.
- 2. Needle valve: see page 19.

# PA3 & PA32 PICK & PLACE ACTUATORS



Above figures are computed; output torques and forces are reduced by internal friction.

# UNCONTROLLED IMPACT CAN CAUSE DAMAGE. **LIMIT BOTH ROTATIONAL & LINEAR SPEEDS BY** USE OF FLOW CONTROL IN EXHAUSTING CYLINDER.

# **MAGNETIC SWITCH OPTIONS**

Reed (G) and solid state switches (R or S) are available on rotary and linear sections of unit. Switches mount to cylinders; place as required for access and phasing.

## **ROTARY INSTALLATIONS:**

Find C dimension in tables on A3 & A32 page.

# LINEAR INSTALLATIONS:

Add 1 1/2" to cylinder length and unit height

# **MAXIMUM RATINGS**

		PA3	PA32
ROTARY	PRESSURE, AIR	165	165
SECTION	PRESSURE, OIL	165	165
LINEAR	PRESSURE, AIR	250	250
SECTION	PRESSURE, OIL	500	500
TORQUE,	NON-SHOCK, INLB.	250	250
Rot. Act. D	isp: in ³/deg.	.026	.052
Weight 180	deg., 2" std. unit: lb.	9.2	11.9

Rotation Tolerance:

PA3 & PA32 -0 +2 deg

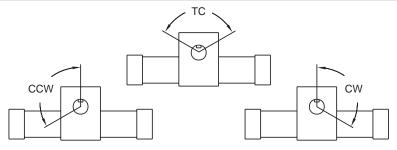
Backlash: PA3

2 deg.

PA32 1 deg.

- 1. Stop tubes are available to stabilize the extended shaft. Standard lengths are 1" and 2"; add to unit height. Sleeves for switch magnets serve the same function.
- 2. Needle valve: see page 20.

# **GENERAL AND MOTION CONTROL OPTIONS**

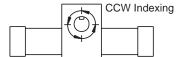


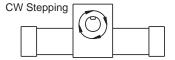
# **ACTUATOR SHAFT KEYWAY MOTION**

Symbols specify orientation of arc of motion looking at front of unit. In Top Center (TC), the keyway passes thru 12:00 o-clock (0 deg.) at the midpoint of rotation; one-half the rotation is on either side of 12:00 o-clock.

Symbol: TC, CW, CCW

No cost option.





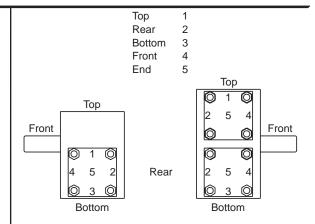
# **INDEXING & STEPPING ACTUATOR SHAFT KEYWAY MOTION**

Specify shaft rotation looking at the projecting, load-carrying shaft.

Symbol: CW, CCW

No cost option.

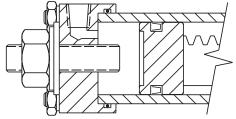
Indexing actuator: steps in specified direction to hard stops. Stepping actuator: steps in specified direction, no hard stops. Accumulates error.



# **PORT POSITIONS 1, 2, 3, 4, 5 NEEDLE VALVE POSITIONS 1, 2, 3, 4** (PORT & NEEDLE VALVE CANNOT BE AT SAME POSITION)

Use numbered locations to specify desired position. No port in position 5 with options A, F or C. No port or needle valve between end caps in dual rack units; for positions 90 from shaft, specify 1, 3 (top and bottom).

Symbols: 1, 2, 3, 4, 5 No cost option.

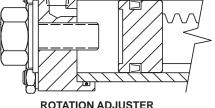


# **ROTATION ADJUSTER**

Adjustable stop controls rotation over 30 deg. range by stroke reduction.

Can be combined with flow control or cushion in single rack actuators or steppers.

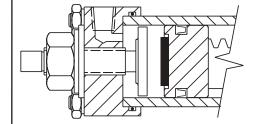
Not available for indexers.



# **BUMPER**

A urethane bumper is fastened to the piston face. It eliminates metal to metal contact and absorbs shock. Requires added cylinder length.

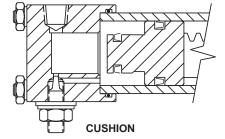
Symbol: Q



# **ADJUSTER AND BUMPER**

Combination of adjuster and bumper. Uses enlarged adjuster face to distribute impact. Requires added cylinder length.

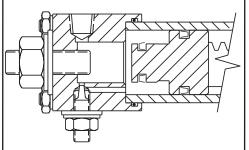
# Symbol: A



A reversed U-cup on the auxiliary piston closes the free passage to the port, forces exhaust through the control needle valve over last 30 deg. of rotation. For return, pressure folds U-cup down, allows full pressure and flow to piston.

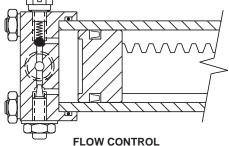
Not fully effective in drive direction in steppers or indexers because of overrunning clutch.

Symbol: C



# **ADJUSTER AND CUSHION**

Combined adjuster and cushion for single rack actuators or steppers. Installed separately, cushion on top rack, in dual rack units. Stroke reduction also reduces cushion action.



Forces exhausting air to pass through control needle valve, limits operating speed throughout rotation in one direction. Check valve opens for full flow on return. Requires needle valve access; not available with port position 5. Intended primarily for air operation. Can be combined with rotation adjustment.

Symbol: F

# **MOTION CONTROL OPTIONS**



#### THREE POSITION ACTUATOR

Uses internal stops for optional drive to any of three shaft positions in any sequence. Available in A12, A22, A32 and A42, but drives shaft with only one cylinder at a time; use torque factor for A1, A2, A3 or A4.

Shown: A42-45-0-45-S11-C2-RR-1/4-1, 3

To specify the positions desired in a 3 position dual rack actuator:

- 1. Determine central reference position RP at 0; to 360; clockwise from 12:00
- 2. Determine angle CCW from RP: A
- 3. Determine angle CW from RP: B



Specify: A-RP-B



Example: 30-45-30

NOTE: MULTI-POSITION ACTUATORS
REQUIRE TWO MAGNETIC SWITCHES TO
INDICATE EACH INTERMEDIATE POSITION.



#### AIR DAMPERS

Auxiliary cylinders and pistons with adjustable pressurization through a relieving regulator give soft deceleration at cycle rates higher than conventional shock absorbers can tolerate.

Consult factory.



#### FOUR OR FIVE POSITION ACTUATORS

Pairs of auxiliary cylinders and pistons with stop rods added to three position actuators provide additional intermediate stop positions. All positions are accesssible in any sequence. Note that intermediate end caps are vented. Shown: four position A22-30/30-30-30-S5-1/8-4

# **FOUR POSITION:**

To specify the positions desired in a 4 position dual rack actuator with auxiliary cylinders:

- 1. Determine an inner reference position RP at 0; to 360; clockwise from 12:00
- 2. Determine angle CCW from RP: A
- 3. Determine angles CW from RP: B & C Enclose RP with dashes, separate others with slash.



Specify: A-RP-B/C

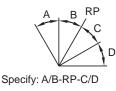


Example: 30-0-30/30

# **FIVE POSITION:**

To specify the positions desired in a 5 position dual rack actuator with auxiliary cylinders:

- 1. Determine the central reference position RP at 0; to 360; clockwise from 12:00
- 2. Determine angles CCW from RP: A & B
- Determine angles CW from RP: C & D Enclose RP with dashes, separate others with slash.





Example: 30/30-30-30/30

# **CONSTRUCTION OPTIONS**



#### **WASHDOWN UNITS**

Shaft seals built into body or integral cover plates, cylinders sealed by O-Rings, assembly threads sealed, stainless shafts, anodized body and end caps.

Symbol: J

On order, hard chrome plated shafts, electroless nickel plated body and end caps.

#### **DUST RESISTANT UNITS**

Units sealed against inward leakage Pressurization port

Symbol: Written description

# **CLEAN ROOM CONSTRUCTION**

Units sealed against outward leakage Body drain or purge ports Low vapor pressure lubrication Dry lubrication or wear rings

Symbol: Written description

#### **SPECIAL SEALS**

High temperature or aggressive fluids: FKM Note bearing seal limitations.

Symbol: V

Minimum fluid leakage: Pretensioned seals. Check fluid compatibility. Note increased breakaway pressure.

Symbol: T

# HIGH PRESSURE CONSTRUCTION

For pressures to 750 psi. Steel cylinders (no magnetic switches), hydraulic pistons with backup rings or pretensioned seals as required. Thread inserts on tie rod anchors. Body drain if desired.

Symbol: HP

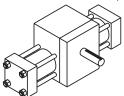
# HEAVY DUTY, DUST RESISTANT A4, A42, X4, X42

Sealed, non-pumping structure-dust stays out. Pistons: two PTFE wear rings, carboxylated nitrile seals.

Cylinders: hard chrome ID, epoxy OD or aluminum with hard coat ID.

Lube: extra-tacky air cylinder grease. Symbol: A or K

# REAR MOUNT CONSTRUCTION X3, X32, X4, X42



Shaft projects from rear; front mount holes opposite. Specify shaft rotation and options relative to shaft. Note reduced impact capacity page 29.

Symbol: B

# **SIGNAL OPTIONS - MAGNETIC SWITCHES**

# **TIE ROD UNITS**

Two types of clamps are shown. Tie rod or strap clamps are supplied to fit best on the unit for which they are specified.

# **UNITS WITHOUT TIE RODS** A032 A752 AL75 Switch position is adjustable along the integral track and

Switch position is adjustable along the integral track and locked by a hex socket set screw. Pigtail leads with connectors as shown on the A752 are optional on all switches; the extension cables should be ordered separately.

# **SET UP AND OPERATION**

Adjust switch position along exhausting cylinder to phase signal for desired sequence.

Adjustable range: 30 deg. or 1/2 stroke, whichever is smaller.

Keep magnetic materials away.

Multi-position actuators require two switches to indicate each intermediate position; a single switch will indicate each end position.

Rotomation piston magnets and switches are designed to work together. Magnets or switches may or may not work with components of other manufacture.

# **MAGNETIC SWITCHES**

# SWITCHES FOR TIE ROD UNITS SWITCHES FOR A032, A752 & AL75

# **SWITCHES FOR PBM**

	R	s	G	R	s	R	s	
SWITCHING VOLTAGE	6-24 VDC	6-24 VDC	5-120 VAC/VDC	6-24 VDC	6-24 VDC	5-30 VDC	5-30 VDC	
SWITCHING CURRENT	.5 A Max.	.5 A Max.	.5 A Max., .005 Min.	.20 A Max.	.20 A Max.	.20 A Max.	.20 A Max.	
SWITCHING POWER	12 W Max	12 W Max	10 W Max.	4.8 W Max	4.8 W Max	6 W Max Resistive	6 W Max Resistive	
VOLTAGE DROP	.5 V	.5 V	3.5 V	1.0 V Max.	1.0 V Max.	1.1 V Max.	1.1 V Max.	
'R' NPN (Sinking)	SWITCH	BRN — LOAD	6-24 VDC POWER SUPPLY	L: 937-000-032 BRN BLK C: 937-000-332 BLU	5-30 VDC POWER SUPPLY			
'S' PNP (Sourcing)	SWITCH	BRN — LOAD	6-24 VDC POWER SUPPLY	L: 937-100-031 BRN SWITCH BLK LC	6-24 VDC POWER SUPPLY	SWITCH BLK LC	5-30 VDC POWER SUPPLY	
'G' Reed	L: 837-100-004 SWITCH C: 837-100-104 N/A on A1, X1, S1	- BRN — LOAD - WHT — & PA01	5-120 V DC or AC POWER SUPPLY	N/A	A	N//	4	

# **SWITCH LEADS:**

Description Specify

9 ft. PVC cable, 3 conductor, Color coded.

6 inch. pigtail with 8 mm Cquick disconnect.

# **EXTENSION CABLES - ORDER SEPARATELY**

Cables have 8mm locking connector to connect to C switches, above. 3 conductors color coded brown, black, blue.

Cable length	Part Number
2 m	CC2
5 m	CC5

# **REPLACEMENT SWITCHES**

Order by number adjacent to switch block in diagrams above. Switches with leads identified by L, those with pigtail and connector by C. Switches are tested before shipment and are **NOT** returnable.

Extension cables have same color coding as A032, A752 and AL75 switches above, right.

LED indicates switch operation.

Standard lead length is 9'; connector is on 6" pigtail.

Observe polarity; reversal will damage switch.

Observe maximum ratings; exceeding them will damage switch.

Reed switch has built-in surge protection; others do not.

Switches and cables resistant to moisture, dust and oil: designed to meet NEMA 4 specification.



# **OTHER SIGNAL OPTIONS**



# MAXIMUM LOAD TORQUE ON EXTENDED PAWL SHAFT

Unit	In. Oz.
X1 or X12	1
X2 or X22	2
X3 or X32	10
X4 or X42	17

# INDEXING ACTUATOR EXTENDED PAWL SHAFT

Shaft rotates 7 deg. at index and reset. Arm actuates switch, prox detector or pilot valve. Dimensions: see Design Your Indexing Actuator page 24.



# **SIGNAL PORT**

For use in explosive or other atmospheres or with air logic controls. Ports provide line pressure signal at ends of rotation to actuate external devices. Fixed position, not adjustable.

# **MOUNT PLATE OPTIONS**



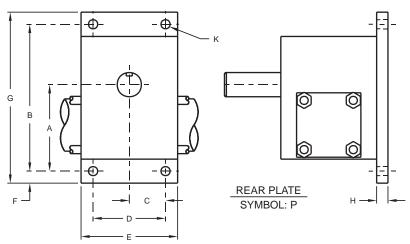


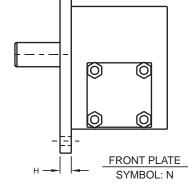


FRONT MOUNT PLATE N



**BOTTOM MOUNT PLATE M** 





<u>INDEXING ACTUATORS:</u> Rear plate P fits X1, X12, X2, X22; for X3, X32, X4 & X42 specify BP: rear mount construction and plate.

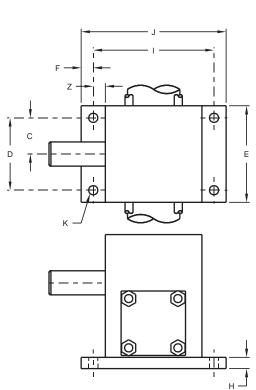
STEPPING ACTUATORS: Rear plate P not usable on S2 OR S22; others ok.

PICK AND PLACE ACTUATORS AND NITPICKERS: Mount plate P (perpendicular to rod) same as listed plate for corresponding actuator or indexer.

# **DIMENSIONS**

MODEL	Α	В	С	D	Е	F	G	Н	- 1	J	K	Z
A01	1.188	1.875	.313	.625	1.00	3/16	2.25	.175	1.375	1.75	3/16	.188
PA01	1.312	2.000	.750	1.500	2.00	1/4	2.50	.175	NA	NA	13/64	.188
A032	1.000	2.000	.750	1.500	2.00	1/4	2.50	.175	2.000	2.50	7/32	.250
A1	1.500	2.500	.750	1.500	2.00	1/4	3.00	.175	2.500	3.00	7/32	.563
S1	1.500	2.500	.750	1.500	2.00	1/4	3.00	.175	3.125	3.63	7/32	.563
A12	1.500	3.000	.750	1.500	2.00	1/4	3.50	.175	2.500	3.00	7/32	.563
X1	1.500	2.500	.750	1.500	2.00	1/4	3.00	.175	3.125	3.63	7/32	.250
X12	1.500	3.000	.750	1.500	2.00	1/4	3.50	.175	3.125	3.63	7/32	.250
A2 or S2	1.938	3.188	.750	1.500	2.50	1/4	3.69	.235	2.500	3.00	7/32	.250
A22 or S22	1.938	3.875	.750	1.500	2.50	1/4	4.38	.235	2.500	3.00	7/32	.250
X2	1.938	3.188	.750	1.500	2.00	1/4	3.69	.235	3.500	4.00	7/32	.250
X22	1.938	3.875	.750	1.500	2.00	1/4	4.38	.235	3.500	4.00	7/32	.250
A3 or S3	2.687	4.562	1.125	2.250	3.00	3/8	5.31	.350	3.750	4.50	9/32	.375
A32 or S32	2.687	5.375	1.125	2.250	3.00	3/8	6.13	.350	3.750	4.50	9/32	.375
Х3	2.687	4.562	1.125	2.250	3.00	3/8	5.31	.350	4.500	5.25	9/32	.375
X32	2.687	5.375	1.125	2.250	3.00	3/8	6.13	.350	4.500	5.25	9/32	.375
A4 or S4	3.125	5.063	1.125	2.250	3.00	3/8	5.81	.350	3.750	4.50	11/32	.375
A42 or S42	3.125	6.250	1.125	2.250	3.00	3/8	7.00	.350	3.750	4.50	11/32	.375
X4	3.125	5.063	1.125	2.250	3.00	3/8	5.81	.350	4.750	5.50	11/32	.375
X42	3.125	6.250	1.125	2.250	3.00	3/8	7.00	.350	4.750	5.50	11/32	.375

For PA01, see pg. 35



BOTTOM PLATE SYMBOL: M

# MATCH YOUR LOAD WITH SHAFT OPTIONS



# **DOUBLE END SHAFT**

Shaft extends from the rear of the unit as well as the front. Rear projection dimensions same as front.

Symbol: D(SIZE)

A42-180-CCW-D11-3C2-1/4-1&3 shown.

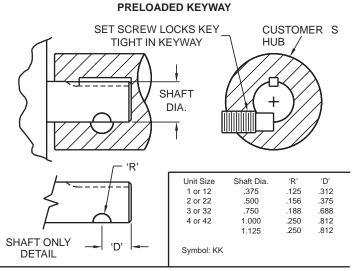


#### **HOLLOW SHAFT**

Provides compact coupling to load; dimension table below. Self aligning if mounted free on driven shaft with turnbuckle to absorb torque.

Symbol: HS(SIZE)

A42-180-TC-HS75-3C2-1/4-1&3 shown.



# STANDARD AND OPTIONAL SHAFT CONFIGURATIONS

#### **REAR PROJECTING SHAFT** A032



Specify options from front view of unit. Rear projecting shaft operates like rear half of double ended shaft.

SHAFT DIAMETER:	3/16		1/4			3/8		3/8 ID	1	/2		3/4		3/4 ID		1		1 1	1/8
SHAFT SYMBOL:	S18	S25	D25	R25	S37	D37	R37	HS37	S5	D5	S75	D75	R75	HS75	S10	D10	R10	S11	D11
UNIT SYMBOL:																			
A032		0	0	0	S	0	0*												
A01	0	S	0																
A1 or A12		0			S	0		0											
S1					S														
X1 or X12					S	0													
AL75		S	0	0															
A752					S	0		0											
A2 or A22								0	S	0									
S2 or S22									S	0									
X2 or X22									S	0									
A3 or A32											S	0		0					
S3 or S32											S								
X3 or X32											S	0	0						
A4 or A42														0	S	0		0 *	0
S4 or S42															S	0			
X4 or X42															S	0	0		

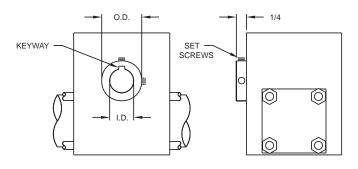
Abbreviations: "S18" means "single ended shaft .188" (3/16") diameter; others similar.

"D18" means "double ended shaft .188" (3/16") diameter; others similar. "R37" means "rear projecting shaft .375" (3/8") diameter; others similar. "HS37" means "hollow shaft .375" (3/8") inside diameter; others similar.

"S" means "standard". "O" means "optional".

# **HOLLOW SHAFT**

UNIT	SHAFT SYMBOL	SHAFT I.D.	KEYWAY	SHAFT O.D.	STD. BRG.	SET SCREW
A1, A12 & A752	HS37	.3755/.3765	3/32 X 3/64	.625	BRONZE	8-32
A2, A22	HS37	.3755/.3765	3/32 X 3/64	.750	BALL	8-32
A3, A32	HS75	.751/.752	3/16 X 3/32	1.378	BALL	10-32
A4, A42	HS75	.751/.752	3/16 X 3/32	1.378	BALL	10-32



#### SPECIAL SHAFTS:

Specify or sketch:

Length or projection

Diameter

Keyway Drill or tap

Retaining ring groove

Bore

Wrench flats

Material

Heat treat

**Plating** 

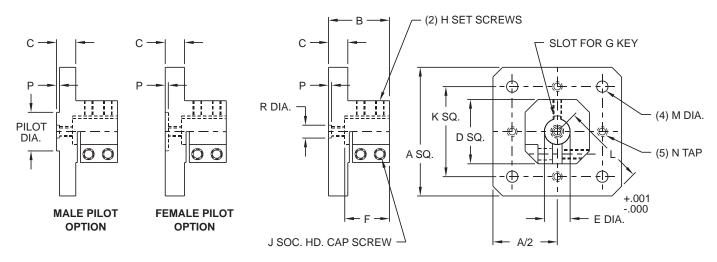
Most configurations in short

time at low cost.

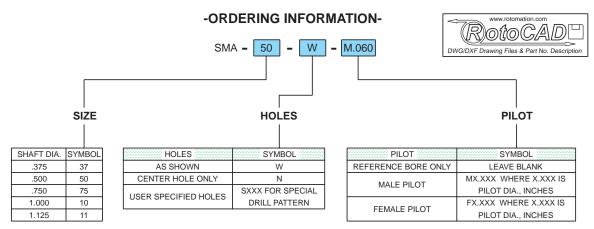
Ask for quotation.

<sup>\*</sup> No cost option; all other optional shaft configurations at slight additional cost.

# **SHAFT MOUNTING ADAPTERS**



								DIMENS	IONS							
SIZE	SHAFT DIA.	A	В	С	D	E	F	G	Н	J	K	L	М	N	Р	R
37	.375	2.00	1.063	.313	1.00	.375	.750	3/32 X .75 LG.	6-32	#8-32	1.375	1.22	.219	#10-32	.060	.250
50	.500	2.50	1.188	.375	1.25	.500	.813	1/8 X .81 LG.	6-32	#10-32	1.750	1.64	.219	#10-32	.060	.250
75	.750	3.50	1.875	.500	1.63	.750	1.375	3/16 X 1.38 LG.	10-32	1/4-20	2.500	2.25	.281	1/4-20	.060	.313
10	1.000	4.00	2.125	.625	2.25	1.000	1.500	1/4 X 1.50 LG.	1/4-20	5/16-18	3.000	2.56	.406	3/8-16	.125	.438
11	1.125	4.00	2.125	.625	2.25	1.125	1.500	1/4 X 1.50 LG.	1/4-20	5/16-18	3.000	2.56	.406	3/8-16	.125	.438



# NOTES:

- NOTES:

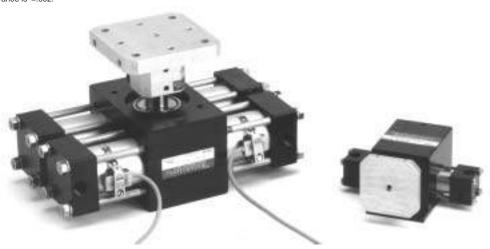
  1. Material: Clear anodized aluminum.

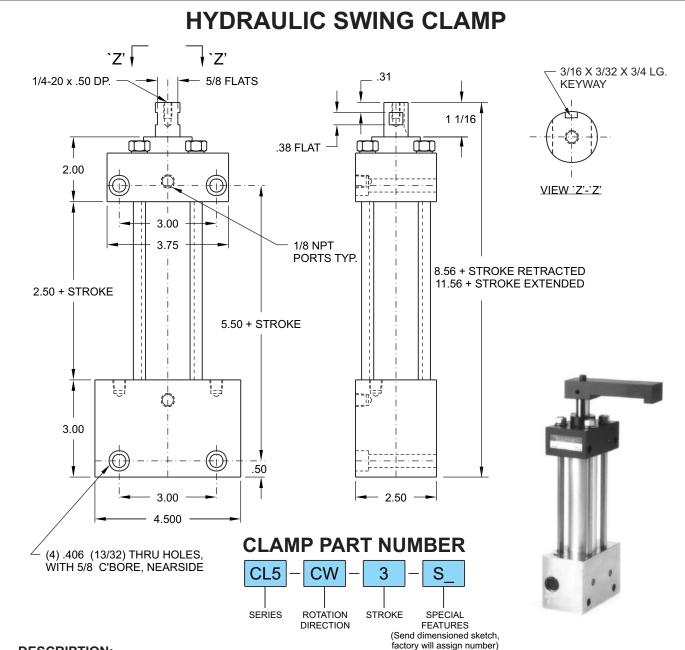
  2. User specified holes: Send drawing. Factory will assign number XXX.

  3. Adapters are stocked with no holes and with holes as shown. Special hole patterns and pilots are normally added after anodize and will expose bare aluminum.
- 4. Keyway is aligned with sides of plate. Reference bore 'R' is concentric with shaft bore within .001 TIR.

  5. Shaft mounting adapters shipped with key, clamp screws & set screws.

  6. Pilot diameter tolerance is ±.002.





# **DESCRIPTION:**

Clamp rod and arm extended and retracted by 1.375 bore cylinder with .750 diameter rod. Rod and arm rotated 90 deg. by rack and pinion actuator. Extend/retract and rotation separately plumbed and controlled.

# **RATINGS**

Maximum Working Pressure, p.s.i.:	500
Maximum Clamping Force, lbs.:	528
Maximum Extend Force, lbs.:	742
Clamp Arm Rotation, deg.:	90
Bore Diameter:	1.375"
Rod Diameter:	.750"

# **OPTIONS**

Stroke:	.5" To 8"
Ports:	1/8" NPT

# **CONSTRUCTION:**

Rod: Chrome Plated 303 Stainless Steel Body: 6061 Aluminum, Electroless Nickel Plated End Cap: 2024 Aluminum, Black Anodized Tie Rods & Nuts: 303 Stainless Steel

# **SPECIAL ORDER:**

Rod End Detail: Send Dimensional Sketch Port & Mount Hole Size & Location Materials Finishes

# **READY REFERENCE - INSTALLATION & OPERATION**

## **GENERAL**

Torque and thrust data given in the brochure are theoretical and intended as a guide to performance. Applications, including specification of required unit size, etc. are the responsibility of the user. Rotomation will handle repair or replacement expeditiously, making all reasonable efforts to provide same day shipment via overnight air on items received by that routing, but cannot be responsible for consequent or other related costs.

Improvements are frequent and designs are subject to change without notice; mounting dimensions are kept unaltered for interchangeability.

User notation of the invoice number or the serial number stamped on the unit body will enable duplication of prior units.

# **ACTUATOR AND INDEXER SHOCK LOADS**

In many cases, an actuator or indexer must be sized for the load it will stop rather than the operating torque requirement. Avoid impact loads caused by load momentum; their energy can break the shaft or gear and rack teeth; they are the primary cause for catastrophic failure.

The best way to control impact is to reduce the load inertia as much as feasible and then to limit its angular velocity. Determine the dwell time needed at the work station, then use as much as possible of the remaining time for transport by controlling rotational speed with flow control of the exhausting cylinder.

External stops, with or without shock absorbers, should be used in severe actuator installations. If external stops are not practical, auxiliary cylinders and pistons with an adjustable external air supply can be fitted to absorb load energy. Internal cushions will quiet a light load but will not dissipate a significant amount of load energy.

For an indexer, external shock absorbers can be effective if properly installed to allow full angular travel of the load.

# **ACTUATOR ROTATION AND POSITION ACCURACY**

The tolerance of the angle of shaft rotation is shown in the table on page 5. The tolerance on keyway position at the ends of rotation is one-half of the rotation tolerance plus one degree. For example, an A3-90-CW... shaft will rotate through 90 to 92 deg. (-0° +2° tolerance). Its keyway will start between 358° and 0° (1/2 x 2° + 1° tolerance) and will finish rotation between 90° and 92° (1/2 x 2° + 1° tolerance).

# **BACKLASH IN ACTUATORS**

Rotomation dual rack actuators are arranged so that at the end of stroke the tooth backlash distance is taken up by one-half the unit torque. Order the dual rack configuration to achieve this position accuracy without external stops.

In single rack actuators there is ordinarily some backlash at the ends of rotation. See table, page 5 for maximum values.

# **CONTROL COMBINATIONS**

Not all controls can be combined at one end of a cylinder. Combinations of controls are possible in a two rack unit which provide functional and access advantages. Combination of flow control and cushion or cushion and rotation adjuster can be set up on different racks, can be placed at one end or the other to improve access or installation arrangements.

# TORQUE REQUIREMENT

Specification of an actuator or other rotary device should begin with the load torque requirement with margin to account for variations in load, system pressure at the actuator and friction in the actuator (See "Breakaway Friction"). Actuator and load static friction occur at the start of the cycle and must be allowed for. Load torque should be measured rather than computed to avoid errors from unanticipated factors. Temporary torque arms and "fish scale" force measurements will usually suffice. With the load torque known, a device can be specified on the basis of minimum system pressure and a reasonable margin; 40% is used by many designers to assure reliable production.

# **BREAKAWAY FRICTION**

The pressure energized nitrile seals used allow breakaway at low pressure. Actuators and steppers start and move smoothly at or below 5 psi, indexers below 7 psi, and pick and place and nitpicker units below 15 psi. Pretensioned seals or seals of FKM increase this pressure to as much as 25 psi.

# **DUAL RACK INDEXING AND STEPPING ACTUATORS**

Many applications involve moving a load which is primarily inertia. In this case, the limiting factor for an indexing actuator is its ability to stop the load. The only reason to specify a dual rack actuator is for an application with a high torque, low inertia load, such as friction, bending, or lifting.

# INDEXING AND STEPPING ACTUATOR TORQUE RATINGS

The maximum torque is limited by the roller clutches used to drive the shaft and to prevent reverse rotation. Exceeding the maximum working pressure specified may overload the clutch, reducing life and/or causing immediate failure. Dual rack actuators are intended for use in applications where the maximum torque rating of the clutch cannot be utilized on normal shop air. Please note that normal shop air may overload the clutch on a dual rack indexing or stepping actuator. Reverse torque from an external source can also damage the actuator if it exceeds the maximum torque rating.

#### **MAXIMUM OPERATING RATES**

Rotomation devices are capable of operating at rates as high as hundreds of cycles per minute, but the angular momentum of most loads will limit the usable rate. See "Actuator and Indexer Shock Loads". System and cycle design should begin with identification of the total amount of time available for load transport, allowing necessary dwell time for machine or manual operations. With the cycle set up to utilize this time, the load motion can be slowed as far as possible and the effects of load velocity minimized. Especially with high cycle rates, it is wise to limit impact velocity by use of flow control in the exhausting cylinder or by lowered system pressure. Impacts which cause torsional vibration or bounce will generally cause failure of parts.

# **PHONE & FAX SUPPORT**

For technical support and additional information, call 386-676-6377 or fax 386-676-6379.

# **READY REFERENCE - CONTINUED**

# PNEUMATIC OPERATION AND LUBRICATION

With clean air, normal loading and noncorrosive environment, Rotomation actuators will operate for millions of cycles without added lubrication. For maximum life with high cycle rates and/or less clean environment, the heavy duty (A, K or J) options should be specified and/or airline lubrication utilized. Lubricators should be appropriately sized, positioned to allow downward flow to the actuator and kept filled with lubricant compatible with the seals in use.

# **FLUID MEDIUM AND SEALS**

Use a good, clean fluid compatible with the seals in dynamic applications. Seals are of nitrile (Buna) unless specified otherwise; check the fluid in use. If other seals materials have been specified, particular attention is required. Polyurethane, used in pretensioned seals, is not compatible with automatic transmission fluid and a number of widely used petroleum based fluids. Where high temperature or aggressive fluids (as phosphate esters) are encountered, specify fluorocarbon seals. Pretensioned seals and some seal compounds cause increased cylinder friction, raising the breakaway pressure to as much as 25 psi.

#### **OIL LEAKAGE**

Hydraulic units will, in general, suffer some leakage. Piston seal leakage will be apparent ultimately as leakage from the body, and will occur in either air/oil or hydraulic installations. The amount is usually small, resulting from the relaxation of the seal when pressure is removed, either during normal cycling or shutdown. This oil can be disposed of by the installation of a drain connection to the body which will be supplied upon request; specify mount orientation for correct location. Pretensioned seals will markedly reduce leakage. However, these seals increase breakaway pressure as much as 25 psi, which is negligible in most hydraulic systems but is not tolerable in some air/oil applications. Multiple seals may be effective in some instances. Consult the factory.

#### **AIR/OIL INSTALLATIONS**

Air/oil systems provide close control and smooth motion but operate at relatively low rotation rates unless large passages and valves are provided for high flow rates at low pressure differentials. Conventional air/oil systems use air/oil tank for each direction with a flow control in each air or oil line, depending upon the degree of control required. Slow, uniform motion in one direction and faster motion in the other can be achieved using an air/oil tank and cylinder on one side, and straight air, flow controlled in exhaust, on the other side. Seals and fluid should be carefully selected to achieve desired motion and leak characteristics.



# **FLOATING PISTONS**

Floating pistons provide many operating advantages, they may require special attention during set up when the shaft is moved manually without pressure in the cylinders to keep the pistons against the ends of the rack; the pistons often stick against the end caps, leaving the rack free. The result is that the piston will make a noisy impact against the rack when pressure is applied. In case of a unit with magnetic pistons, the uncertainty of piston location can lead to errors in setting the operating point of magnetic switches; use a low pressure to retain the pistons if manual positioning is required. All Rotomation units except the following have floating pistons: A032, A01, A1, S1, X1, X12, AL75, A752 and PA01; these units have captive pistons.

# INTERNAL LUBRICATION

The internal lubrication applied in factory assembly will ordinarily last the life of the unit. Only if the unit is operated at extreme rates or is subject to temperatures high enough to cause displacement of the grease should added lubrication be required. 1/2 to 1 teaspoon of general purpose lithium based grease may be placed on the rack teeth and cylinders at the time of installation of replacement seals or other repair. The cylinders and seals are lubricated in assembly with a lithium based grease containing suspended PTFE.

NOTE: Units manufactured prior to early 1987 had grease fittings or plugs. These have been eliminated to avoid possibility of jamming the unit by excess lubricant.

#### LOAD COUPLING

The load hub should fit the shaft closely and the key be of correct size and length to make a firm fit using all available keyway length. Tighten the set screw over the key firmly, retaining its position with thread locking adhesive.

# ADJUSTABLE LOAD COUPLING

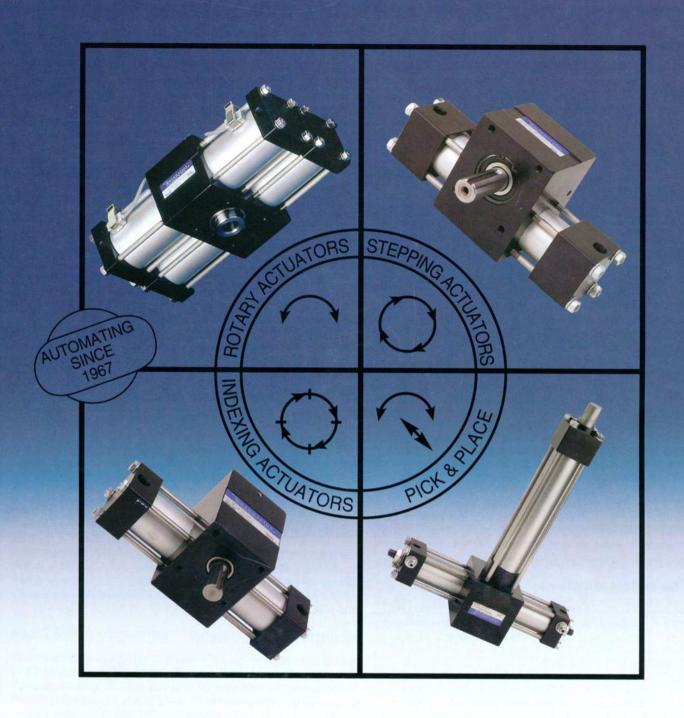
For a hard coupling allowing angular adjustment of the load position, a self-locking coupling (Ringfeder, etc.) can be used directly on the Rotomation and using shafts. Couplers must be carefully installed and tightened; they require wrench clearance and precise shaft alignment.

# **MOUNTING AND ALIGNMENT**

Where possible, provide a compliant coupling between the Rotomation unit and its load. If a hard coupling to a firmly supported shaft is required, provide adjustment of the angle and position of the Rotomation shaft using shims, slotted holes or other means. With mount screws installed and at intended torque, test for free rotation of the shaft and unit. See "Hollow Shaft" below.

# **HOLLOW SHAFT ACTUATOR INSTALLATION**

For a compact, self-aligning installation, place the hollow shaft actuator over the driven shaft, allowing the weight of the actuator to be carried by the shaft and its bearings. Arrange a turnbuckle to take the actuator torque by attaching one end to the actuator by a bracket to mount holes, and the other to the using assembly. The actuator thus remains in alignment with the shaft; adjust the turnbuckle to set the keyway position precisely.



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